

Outline Preliminaries, definitions and results The tools The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps non-orientable surfaces The proof for continuous self-maps non-orientable surfaces	Outline Preliminaries, definitions and results The tools The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps non-orientable surfaces Periodic point free continuous maps on non-orientable surfaces Periodic point free continuous maps on non-orientable surfaces Periodic point free continuous maps on non-orientable surfaces
A discrete dynamical system $(\mathbb{M}, f)$ is formed by a topological space $\mathbb{M}$ and a continuous map $f : \mathbb{M} \to \mathbb{M}$ . A point $x$ is called fixed if $f(x) = x$ , and periodic of period $k$ if $f^k(x) = x$ and $f^i(x) \neq x$ if $0 < i < k$ .	A discrete dynamical system $(\mathbb{M}, f)$ is formed by a topological space $\mathbb{M}$ and a continuous map $f : \mathbb{M} \to \mathbb{M}$ . A point $x$ is called fixed if $f(x) = x$ , and periodic of period $k$ if $f^k(x) = x$ and $f^i(x) \neq x$ if $0 < i < k$ . We denote the set of periods of all the periodic points of $f$ by Per( $f$ ).
Outline         Preliminaries, definitions and results         The proof for continuous self-maps on orientable surfaces         The proof for continuous self-maps on orientable surfaces         The proof for continuous self-maps non-orientable surfaces	Outline         Preliminaries, definitions and results         The tools         The proof for continuous self-maps on graphs         The proof for continuous self-maps on orientable surfaces         The proof for continuous self-maps non-orientable surfaces         Periodic point free continuous maps on non-orientable surfaces         Periodic point free continuous maps on non-orientable surfaces
	The following two results are well known: Let $f : \mathbb{S}^1 \to \mathbb{S}^1$ be a continuous map of degree $d$ . If $Per(f) = \emptyset$ (i.e. if $f$ is periodic point free), then $d = 1$ .
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Outline Preliminaries, definitions and results The tools The proof for continuous self-maps on graphs The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps non-orientable surfaces	Basic definitions What kind of results we want to obtain? Periodic point free continuous maps on graphs Periodic point free continuous maps on orientable surfaces Periodic point free continuous maps on non-orientable surfac	Outline Preliminaries, definitions and results The tools The proof for continuous self-maps on graphs The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps non-orientable surfaces	Basic definitions What kind of results we want to obtain? Periodic point free continuous maps on graphs Periodic point free continuous maps on orientable surfaces Periodic point free continuous maps on non-orientable surfac
The following two results are we	ll known:	The following two results are we	ll known:
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		LI. Alsedà, S. Baldwin, J. Llibre, Minimal sets of periods for torus Pacific J. of Math. <b>169</b> (1995), 1	maps via Nielsen numbers,
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Our objective is two extend the p continuous self–maps on graphs		Our objective is two extend the p continuous self-maps on graphs The tools used for proving these studying the periodic point free other compact absolute neighbo	s and surfaces. e results can be applied for continuous self-maps of many
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**Basic definitions** What kind of results we want to obtain? Periodic point free continuous maps on graphs Periodic point free continuous maps on orientable surfaces Periodic point free continuous maps on non-orientable surface

# **GRAPH THEOREM**

Let G be a connected compact graph such that  $\dim_{\mathbb{Q}} H_1(\mathbb{G},\mathbb{Q})$ = *r*, and let *f* :  $\mathbb{G} \to \mathbb{G}$  be a continuous map.

If  $Per(f) = \emptyset$ , then the eigenvalues of  $f_{*1}$  are 1 and 0, this last with multiplicity r - 1.

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Outline

The tools

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Of course, as a corollary of the GRAPH THEOREM it follows the mentioned result for the circle:

Outline

The tools

Preliminaries, definitions and results

The proof for continuous self-maps on graphs

The proof for continuous self-maps on orientable surfaces

The proof for continuous self-maps non-orientable surfaces

**Basic definitions** 

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Outline Preliminaries, definitions and results The tools

The proof for continuous self-maps on graphs The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps non-orientable surfaces **Basic definitions** What kind of results we want to obtain? Periodic point free continuous maps on graphs Periodic point free continuous maps on orientable surfaces Periodic point free continuous maps on non-orientable surface

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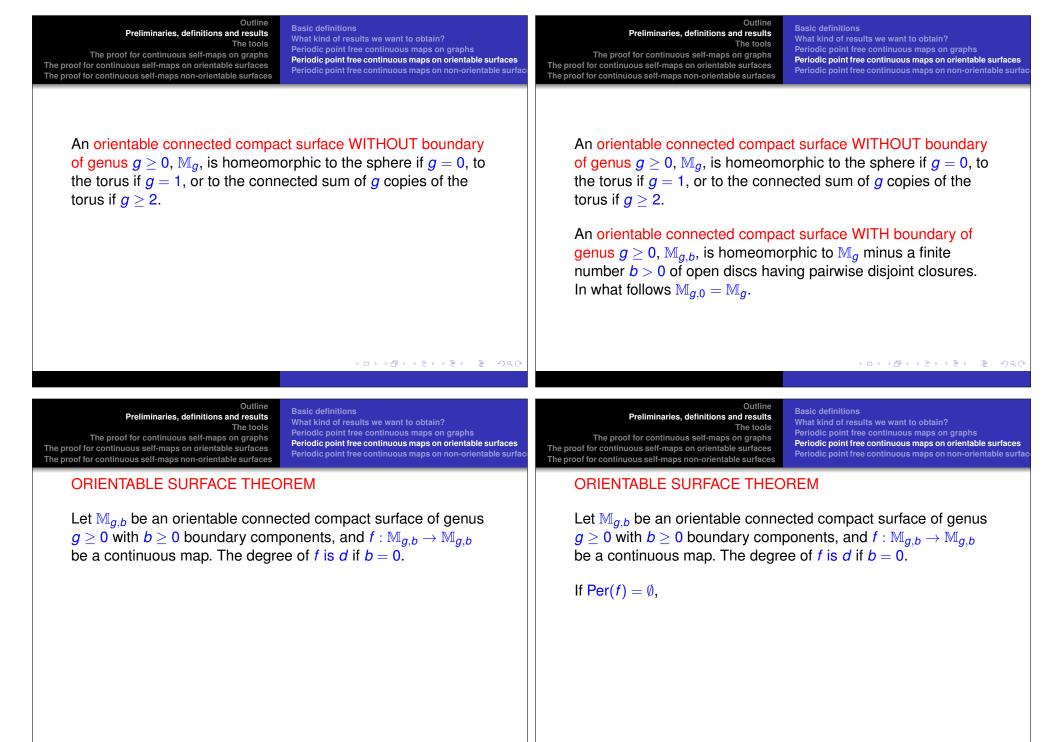
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Let  $f: \mathbb{S}^1 \to \mathbb{S}^1$  be a continuous map of degree d. If  $Per(f) = \emptyset$ , then d = 1.

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What kind of results we want to obtain?

Periodic point free continuous maps on graphs



### Outline Basic definitions

Preliminaries, definitions and results The tools file continuous colf meno on graphs file continuous maps on graphs

The proof for continuous self-maps on graphs The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps non-orientable surfaces

### ORIENTABLE SURFACE THEOREM

Let  $\mathbb{M}_{g,b}$  be an orientable connected compact surface of genus  $g \ge 0$  with  $b \ge 0$  boundary components, and  $f : \mathbb{M}_{g,b} \to \mathbb{M}_{g,b}$  be a continuous map. The degree of f is d if b = 0.

If  $Per(f) = \emptyset$ , then the eigenvalues of  $f_{*1}$  are 1, d and 0, this last with multiplicity 2g - 2 if b = 0 and  $g \ge 1$ ;



Basic definitions What kind of results we want to obtain? Periodic point free continuous maps on graphs Periodic point free continuous maps on orientable surfaces Periodic point free continuous maps on non-orientable surfa

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Outline Preliminaries, definitions and results The tools

The proof for continuous self-maps on graphs The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps non-orientable surfaces

#### Basic definitions What kind of results we want to obtain? Periodic point free continuous maps on graphs Periodic point free continuous maps on orientable surfaces Periodic point free continuous maps on non-orientable surfa

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ORIENTABLE SURFACE THEOREM

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Of course, as a corollary of the ORIENTABLE SURFACE THEOREM it follows the mentioned result for the 2-dimensional torus: Outline Preliminaries, definitions and results The tools The proof for continuous self-maps on graphs The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps non-orientable surfaces

Basic definitions What kind of results we want to obtain? Periodic point free continuous maps on graphs Periodic point free continuous maps on orientable surfaces Periodic point free continuous maps on non-orientable surfaces

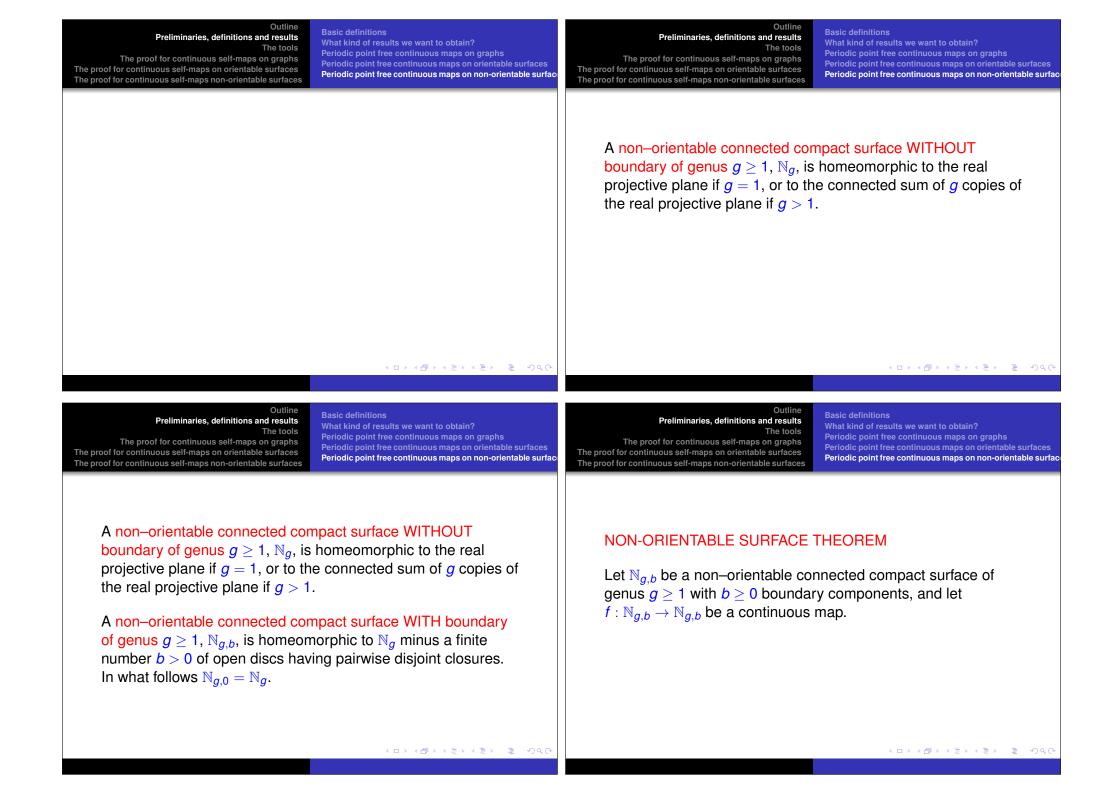
### ORIENTABLE SURFACE THEOREM

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Of course, as a corollary of the ORIENTABLE SURFACE THEOREM it follows the mentioned result for the 2-dimensional torus:

Let  $f : \mathbb{T}^2 \to \mathbb{T}^2$  be a continuous map of degree *d*. If  $Per(f) = \emptyset$ , then the eigenvalues of  $f_{*1}$  are 1 and *d*.



#### Outline Outline Basic definitions **Basic definitions** Preliminaries, definitions and results Preliminaries, definitions and results What kind of results we want to obtain? What kind of results we want to obtain? The tools The tools Periodic point free continuous maps on graphs Periodic point free continuous maps on graphs The proof for continuous self-maps on graphs The proof for continuous self-maps on graphs Periodic point free continuous maps on orientable surfaces Periodic point free continuous maps on orientable surfaces The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps on orientable surfaces Periodic point free continuous maps on non-orientable surface Periodic point free continuous maps on non-orientable surfac The proof for continuous self-maps non-orientable surfaces The proof for continuous self-maps non-orientable surfaces NON-ORIENTABLE SURFACE THEOREM NON-ORIENTABLE SURFACE THEOREM Let $\mathbb{N}_{a,b}$ be a non-orientable connected compact surface of Let $\mathbb{N}_{a,b}$ be a non-orientable connected compact surface of genus $g \ge 1$ with $b \ge 0$ boundary components, and let genus $g \ge 1$ with $b \ge 0$ boundary components, and let $f: \mathbb{N}_{g,b} \to \mathbb{N}_{g,b}$ be a continuous map. $f: \mathbb{N}_{q,b} \to \mathbb{N}_{q,b}$ be a continuous map. If $\operatorname{Per}(f) = \emptyset$ . If $Per(f) = \emptyset$ , then the eigenvalues of $f_{*1}$ are 1 and 0, this last with multiplicity q + b - 2 > 0. ▲□▶▲□▶★□▶★□▶ = つくで ▲□▶▲圖▶▲臣▶▲臣▶ 臣 のへの Outline Outline Preliminaries, definitions and results Preliminaries, definitions and results homology spaces homology spaces The tools Lefschetz number The tools Lefschetz number The proof for continuous self-maps on graphs Periodic point free maps The proof for continuous self-maps on graphs Periodic point free maps The proof for continuous self-maps on orientable surfaces The Lefschetz zeta function $\mathcal{Z}_{f}(t)$ The proof for continuous self-maps on orientable surfaces The Lefschetz zeta function $Z_f(t)$ The proof for continuous self-maps non-orientable surfaces The proof for continuous self-maps non-orientable surfaces Let M be a graph G, or an orientable surface $\mathbb{M}_{q,b}$ , or a Let M be a graph G, or an orientable surface $\mathbb{M}_{a,b}$ , or a non-orientable surface $\mathbb{N}_{a,b}$ . non-orientable surface $\mathbb{N}_{q,b}$ . We denote by $H_k(\mathbb{M}, \mathbb{Q})$ the homological spaces with coefficients in O.

$\begin{array}{c} \text{Outline} \\ \text{Preliminaries, definitions and results} \\ \text{The tools} \\ \text{The proof for continuous self-maps on graphs} \\ \text{The proof for continuous self-maps on orientable surfaces} \\ \text{The proof for continuous self-maps non-orientable surfaces} \\ \text{The lefschetz zeta function } \mathcal{Z}_f(t) \\ \text{The proof for continuous self-maps non-orientable surfaces} \\ The proof for co$	Outline Preliminaries, definitions and results The toolshomology spaces Lefschetz numberThe proof for continuous self-maps on graphs The proof for continuous self-maps on orientable surfacesPeriodic point free maps The Lefschetz zeta function $\mathcal{Z}_f(t)$
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Of course, $k = 0, 1$ if M is a graph,	Of course, $k = 0, 1$ if M is a graph, or $k = 0, 1, 2$ if M is a surface.
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We denote by $H_k(\mathbb{M}, \mathbb{Q})$ the homological spaces with coefficients in $\mathbb{Q}$ . Of course, $k = 0, 1$ if $\mathbb{M}$ is a graph, or $k = 0, 1, 2$ if $\mathbb{M}$ is a	<ul> <li>non-orientable surface N<sub>g,b</sub>.</li> <li>We denote by H<sub>k</sub>(M, Q) the homological spaces with coefficients in Q.</li> <li>Of course, k = 0, 1 if M is a graph, or k = 0, 1, 2 if M is a</li> </ul>
<ul> <li>We denote by <i>H<sub>k</sub></i>(M, Q) the homological spaces with coefficients in Q.</li> <li>Of course, <i>k</i> = 0, 1 if M is a graph, or <i>k</i> = 0, 1, 2 if M is a surface.</li> <li>Each of these spaces is a finite dimensional linear space over</li> </ul>	<ul> <li>non-orientable surface N<sub>g,b</sub>.</li> <li>We denote by H<sub>k</sub>(M, Q) the homological spaces with coefficients in Q.</li> <li>Of course, k = 0, 1 if M is a graph, or k = 0, 1, 2 if M is a surface.</li> <li>Each of these spaces is a finite dimensional linear space over</li> </ul>

Outline Preliminaries, definitions and results The toolshomology spaces Lefschetz numberThe proof for continuous self-maps on orientable surfacesPeriodic point free maps The Lefschetz zeta function $\mathcal{Z}_f(t)$	$\begin{array}{c} \text{Outline} \\ \text{Preliminaries, definitions and results} \\ \text{The tools} \\ \text{The tools} \\ \text{The proof for continuous self-maps on graphs} \\ \text{The proof for continuous self-maps on orientable surfaces} \\ \text{The proof for continuous self-maps non-orientable surfaces} \\ The proof for continuous self-maps non-orient$
Let $\mathbb{M}$ be a graph $\mathbb{G}$ , or an orientable surface $\mathbb{M}_{g,b}$ , or a non-orientable surface $\mathbb{N}_{g,b}$ .	Let <i>n</i> be the topological dimension of a compact polyhedron $\mathbb{M}$ .
We denote by $H_k(\mathbb{M}, \mathbb{Q})$ the homological spaces with coefficients in $\mathbb{Q}$ .	
Of course, $k = 0, 1$ if M is a graph, or $k = 0, 1, 2$ if M is a surface.	
Each of these spaces is a finite dimensional linear space over $\mathbb{Q}.$	
Given a continuous map $f : \mathbb{M} \to \mathbb{M}$ it induces linear maps $f_{*k} : H_k(\mathbb{M}, \mathbb{Q}) \to H_k(\mathbb{M}, \mathbb{Q})$ on the homological spaces of $\mathbb{M}$ .	
Every linear map $f_{*k}$ is given by an $n_k \times n_k$ matrix with integer entries, where $n_k$ is the dimension of $H_k(\mathbb{M}, \mathbb{Q})$ .	< 口 > < 唇 > < 돋 > < 돋 > 이 Q
Outline Preliminaries, definitions and results The toolshomology spaces Lefschetz numberThe proof for continuous self-maps on orientable surfacesLefschetz number Periodic point free maps The Lefschetz zeta function $\mathcal{Z}_f(t)$	$\begin{array}{c c} & & & & \\ & & & & \\ & & & \\ & & & & \\ & & & \\ & & & & \\ & & & & \\ & & & & \\ &$
Let <i>n</i> be the topological dimension of a compact polyhedron M. Given a continuous map $f : \mathbb{M} \to \mathbb{M}$ its Lefschetz number $L(f)$ is defined as $L(f) = \sum_{k=0}^{n} (-1)^{k} \operatorname{trace}(f_{*k}).$	Let <i>n</i> be the topological dimension of a compact polyhedron M. Given a continuous map $f : \mathbb{M} \to \mathbb{M}$ its Lefschetz number $L(f)$ is defined as $L(f) = \sum_{k=0}^{n} (-1)^{k} \operatorname{trace}(f_{*k}).$
	One of the main results connecting the algebraic topology with the fixed point theory is the Lefschetz Fixed Point Theorem which establishes the existence of a fixed point if $L(f) \neq 0$ .

Outline
Preliminaries, definitions and results
The tools
Lefschetz number
proof for continuous self-maps on graphs
Periodic point free maps

The proof for continuous self-maps on graphs The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps non-orientable surfaces

orientable surfaces The Lefschetz zeta function  $\mathcal{Z}_{f}(t)$ 

Let *n* be the topological dimension of a compact polyhedron  $\mathbb{M}$ . Given a continuous map  $f : \mathbb{M} \to \mathbb{M}$  its Lefschetz number L(f) is defined as

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One of the main results connecting the algebraic topology with the fixed point theory is the Lefschetz Fixed Point Theorem which establishes the existence of a fixed point if  $L(f) \neq 0$ .

If we consider the Lefschetz number of  $f^m$ , in general, it is not true that  $L(f^m) \neq 0$  implies that f has a periodic point of period m;

Outline Preliminaries, definitions and results The tools The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps non-orientable surfaces

homology spaces Lefschetz number Periodic point free maps The Lefschetz zeta function  $\mathcal{Z}_{f}(t)$ 

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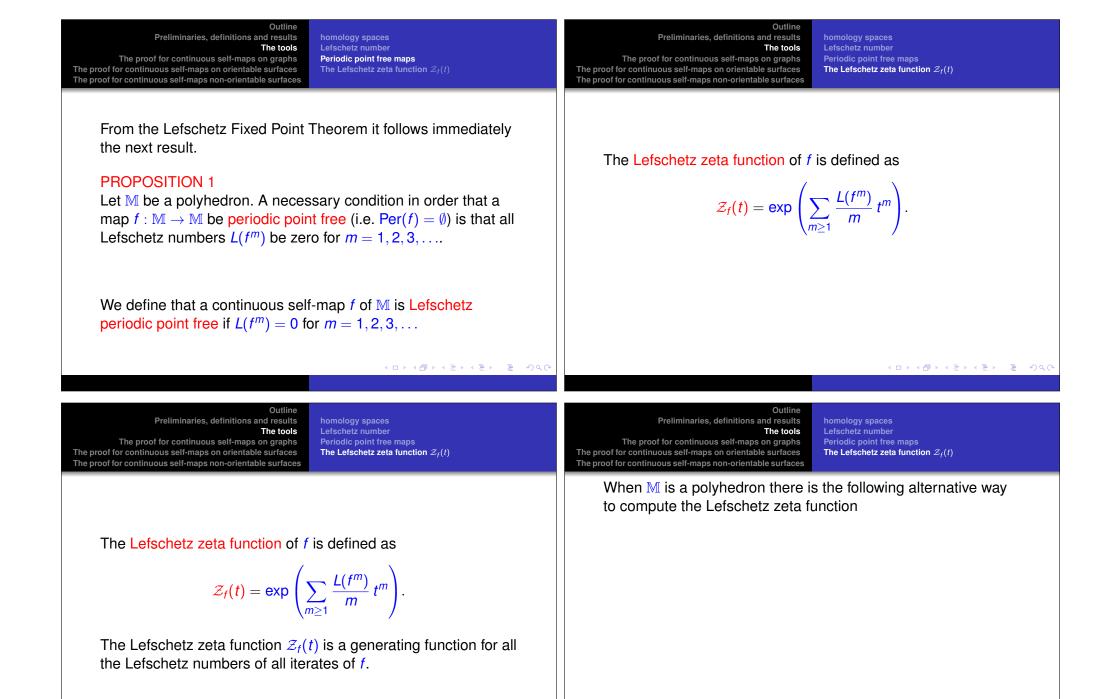
$$L(f) = \sum_{k=0}^{n} (-1)^k \operatorname{trace}(f_{*k})$$

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If we consider the Lefschetz number of  $f^m$ , in general, it is not true that  $L(f^m) \neq 0$  implies that f has a periodic point of period m; it only implies the existence of a periodic point of period a divisor of m.

Outline Outline Preliminaries, definitions and results homology spaces Preliminaries, definitions and results homology spaces Lefschetz number Lefschetz number The tools The tools The proof for continuous self-maps on graphs Periodic point free maps The proof for continuous self-maps on graphs Periodic point free maps The proof for continuous self-maps on orientable surfaces The Lefschetz zeta function  $\mathcal{Z}_{\ell}(t)$ The proof for continuous self-maps on orientable surfaces The Lefschetz zeta function  $\mathcal{Z}_{\ell}(t)$ The proof for continuous self-maps non-orientable surfaces The proof for continuous self-maps non-orientable surfaces From the Lefschetz Fixed Point Theorem it follows immediately From the Lefschetz Fixed Point Theorem it follows immediately the next result. the next result. **PROPOSITION 1** Let M be a polyhedron. A necessary condition in order that a map  $f : \mathbb{M} \to \mathbb{M}$  be periodic point free (i.e.  $Per(f) = \emptyset$ ) is that all Lefschetz numbers  $L(f^m)$  be zero for m = 1, 2, 3, ...

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 Outline
 homology spaces

 Preliminaries, definitions and results
 homology spaces

 The tools
 Lefschetz number

 The proof for continuous self-maps on orientable surfaces
 Periodic point free maps

 The proof for continuous self-maps non-orientable surfaces
 The Lefschetz zeta function  $\mathcal{Z}_f(t)$ 

When  $\mathbb{M}$  is a polyhedron there is the following alternative way to compute the Lefschetz zeta function

$$\mathcal{Z}_f(t) = \prod_{k=0}^n \det(Id_k - tf_{*k})^{(-1)^{k+1}}$$

where  $n = \dim \mathbb{M}$  and  $Id_k$  is the identity map of  $H_k(\mathbb{M}, \mathbb{Q})$ , and by convention  $\det(Id_k - tf_{*k}) = 1$  if  $n_k = 0$ .



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Note that the Lefschetz zeta function is a rational function with integers coefficients,

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Outline Preliminaries, definitions and results The tools The proof for continuous self-maps on graphs

 The tools
 Lefschetz number

 The proof for continuous self-maps on graphs
 Periodic point free maps

 The proof for continuous self-maps on orientable surfaces
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Note that the Lefschetz zeta function is a rational function with integers coefficients, so the power series defining it converges.

Outline Preliminaries, definitions and results The tools The proof for continuous self-maps on graphs The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps non-orientable surfaces

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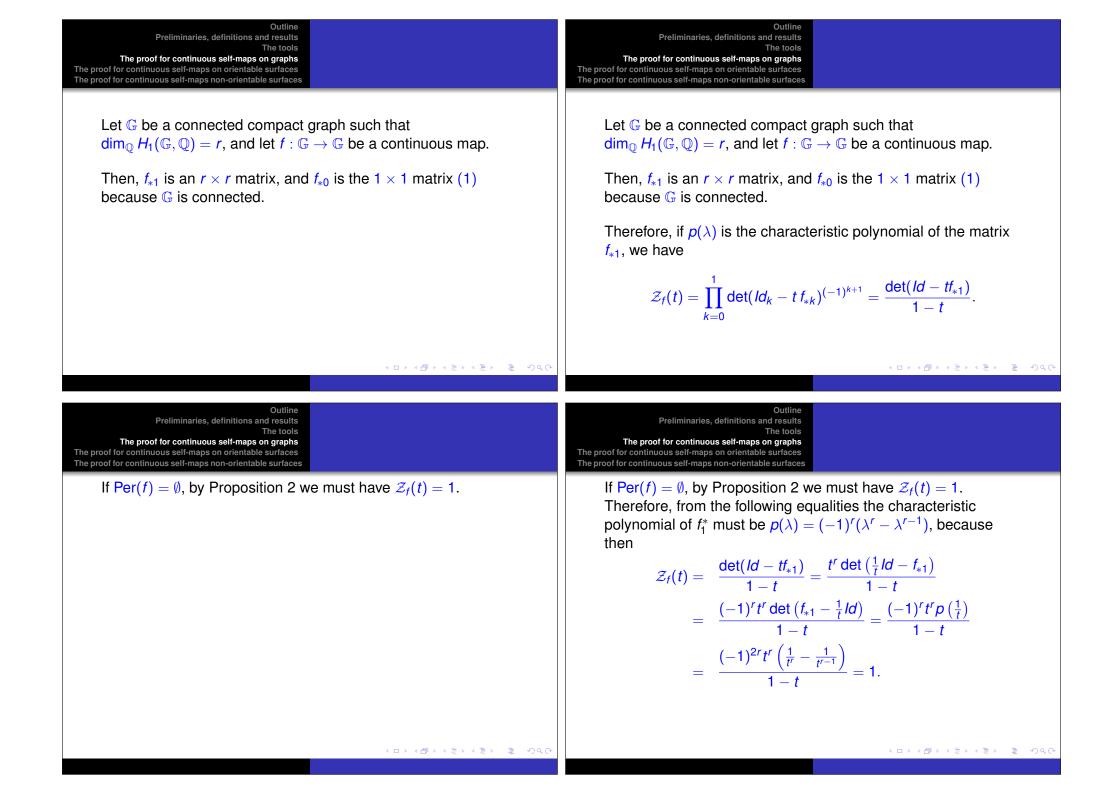
Note that the Lefschetz zeta function is a rational function with integers coefficients, so the power series defining it converges.

Moreover, the Lefschetz zeta function with a finite number of integers (the coefficients of the rational function) keeps the information of the infinite sequence  $\{L(f^m)\}_{m \in \mathbb{N}}$  for m = 1, 2, ...,

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From the definition of Lefschetz zeta function and Proposition 1 it follows immediately the next result.	From the definition of Lefschetz zeta function and Proposition 1 it follows immediately the next result. <b>PROPOSITION 2</b> A necessary condition in order that a map $f : \mathbb{M} \to \mathbb{M}$ be periodic point free is that the Lefschetz zeta function $\mathcal{Z}_f(t) = 1$ .
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The tools The proof for continuous self-maps on graphs The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps non-orientable surfaces	The tools The proof for continuous self-maps on graphs The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps non-orientable surfaces Let G be a connected compact graph such that
	$\dim_{\mathbb{Q}} H_1(\mathbb{G},\mathbb{Q}) = r$ , and let $f : \mathbb{G} \to \mathbb{G}$ be a continuous map.
(ロト (国)・(王)・(王)・(王)・(兄)・(王)・(王)・(王)・(王)・(王)・(王)・(王)・(王)・(王)・(王	(ロト (層ト (音)) (音) (音) (音) (音) (音) (音) (音) (音) (音



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If $\operatorname{Per}(f) = \emptyset$ , by Proposition 2 we must have $\mathbb{Z}_f(t) = 1$ . Therefore, from the following equalities the characteristic polynomial of $f_1^*$ must be $p(\lambda) = (-1)^r (\lambda^r - \lambda^{r-1})$ , because then $\mathbb{Z}_f(t) = \frac{\det(Id - tf_{*1})}{1 - t} = \frac{t^r \det\left(\frac{1}{t}Id - f_{*1}\right)}{1 - t}$ $= \frac{(-1)^r t^r \det\left(f_{*1} - \frac{1}{t}Id\right)}{1 - t} = \frac{(-1)^r t^r p\left(\frac{1}{t}\right)}{1 - t}$	If $\operatorname{Per}(f) = \emptyset$ , by Proposition 2 we must have $\mathcal{Z}_f(t) = 1$ . Therefore, from the following equalities the characteristic polynomial of $f_1^*$ must be $p(\lambda) = (-1)^r (\lambda^r - \lambda^{r-1})$ , because then $\mathcal{Z}_f(t) = \frac{\det(Id - tf_{*1})}{1 - t} = \frac{t^r \det\left(\frac{1}{t}Id - f_{*1}\right)}{1 - t}$ $= \frac{(-1)^r t^r \det\left(f_{*1} - \frac{1}{t}Id\right)}{1 - t} = \frac{(-1)^r t^r p\left(\frac{1}{t}\right)}{1 - t}$
$= \frac{(-1)^{2r}t^r\left(\frac{1}{t^r} - \frac{1}{t^{r-1}}\right)}{1-t} = 1.$ Clearly the zeros of the characteristic polynomial $(-1)^r\lambda^{r-1}(\lambda - 1)$ are 1 and 0, this last with multiplicity $r - 1$ .	$= \frac{(-1)^{2r}t^r\left(\frac{1}{t^r} - \frac{1}{t^{r-1}}\right)}{1-t} = 1.$ Clearly the zeros of the characteristic polynomial $(-1)^r\lambda^{r-1}(\lambda - 1)$ are 1 and 0, this last with multiplicity $r - 1$ . Hence the GRAPH THEOREM is proved.
Outline Preliminaries, definitions and results The tools The proof for continuous self-maps on graphs The proof for continuous self-maps non-orientable surfaces The proof for continuous self-maps non-orientable surfaces	Outline Preliminaries, definitions and results The tools The proof for continuous self-maps on graphs The proof for continuous self-maps non-orientable surfaces The proof for continuous self-maps non-orientable surfaces
	Let $\mathbb{M}_{g,b}$ be an orientable connected compact surface of genus $g \ge 0$ with $b \ge 0$ boundary components, and $f : \mathbb{M}_{g,b} \to \mathbb{M}_{g,b}$ be a continuous map.
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Outline Preliminaries, definitions and results The tools The proof for continuous self-maps on graphs The proof for continuous self-maps non-orientable surfaces The proof for continuous self-maps non-orientable surfaces	Outline Preliminaries, definitions and results The tools The proof for continuous self-maps on graphs The proof for continuous self-maps on orientable surfaces The proof for continuous self-maps non-orientable surfaces
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The degree of $f$ is $d$ if $b = 0$ .	The degree of $f$ is $d$ if $b = 0$ .
	We recall the homological spaces of $\mathbb{M}_{g,b}$ with coefficients in $\mathbb{Q}$ , i.e. $H_k(\mathbb{M}_{g,b}, \mathbb{Q}) = \mathbb{Q} \oplus \mathbb{N} \oplus \mathbb{Q}$ , where $n_0 = 1$ , $n_1 = 2g$ if $b = 0$ ,
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where $n_0 = 1$ , $n_1 = 2g$ if $b = 0$ , $n_1 = 2g + b - 1$ if $b > 0$ ,	where $n_0 = 1$ , $n_1 = 2g$ if $b = 0$ , $n_1 = 2g + b - 1$ if $b > 0$ , $n_2 = 1$ if $b = 0$ ,
<ロ><団><同><定><定><定><定><	<ul> <li>ロ&gt; &lt; 回&gt; &lt; 回&gt; &lt; 回&gt; &lt; 回&gt; &lt; 回&gt; &lt; 回</li> </ul>

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The degree of $f$ is $d$ if $b = 0$ .	The degree of $f$ is $d$ if $b = 0$ .
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where $n_0 = 1$ , $n_1 = 2g$ if $b = 0$ , $n_1 = 2g + b - 1$ if $b > 0$ , $n_2 = 1$ if $b = 0$ , and $n_2 = 0$ if $b > 0$ ;	where $n_0 = 1$ , $n_1 = 2g$ if $b = 0$ , $n_1 = 2g + b - 1$ if $b > 0$ , $n_2 = 1$ if $b = 0$ , and $n_2 = 0$ if $b > 0$ ; and the induced linear maps $f_{*0} = (1)$ , $f_{*2} = (d)$ if $b = 0$ ,
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The degree of $f$ is $d$ if $b = 0$ .	
We recall the homological spaces of $\mathbb{M}_{g,b}$ with coefficients in $\mathbb{Q}$ , i.e. $H_k(\mathbb{M}_{g,b}, \mathbb{Q}) = \mathbb{Q} \oplus \overset{n_k}{\ldots} \oplus \mathbb{Q}$ ,	
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