# On the global dynamics of a three-dimensional forced-damped differential system 

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#### Abstract

In this paper by using the Poincaré compactification of $\mathbb{R}^{3}$ we make a global analysis of the model $x^{\prime}=-a x+$ $y+y z, y^{\prime}=x-a y+b x z, z^{\prime}=c z-b x y$. In particular we give the complete description of its dynamics on the infinity sphere. For $a+c=0$ or $b=1$ this system has invariants. For these values of the parameters we provide the global phase portrait of the system in the Poincaré ball. We also describe the $\alpha$ and $\omega$-limit sets of its orbits in the Poincaré ball.


Keywords: Global dynamics; Poincaré compactification; forced-damped system; invariant algebraic curve; invariant.

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## 1. Introduction and statement of the main results

We consider the autonomous polynomial differential system

$$
\begin{align*}
& \dot{x}=-a x+y+y z \\
& \dot{y}=x-a y+b x z  \tag{1.1}\\
& \dot{z}=c z-b x y
\end{align*}
$$

where $a, b, c$ are real parameters and $b>0$. As usual the dot denotes derivative with respect to the time $t$. This system was proposed and studied by Pehlivan extending a previous study of Craik and Okamoto [2] including linear forcing and damping, for more details on that system and on the notions of forcing and damping see [9]. It is a relevant system because it arises in mechanical,

