Universality and zero-entropy systems New Perspectives in Discrete Dynamical Systems Tossa de Mar, October 2014

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### What is the meaning of universality?

All measure-theoretic systems are assumed standard.

### Definition

A topological dynamical system (Y, S) is **universal** in a class T of measure-theoretic systems if the following two conditions hold:

- For any *S*-invariant measure  $\nu$  on *Y* the measure-theoretic system  $(Y, \nu, S)$  belongs to  $\mathcal{T}$ , and
- So For any system  $(X, \mu, T) \in \mathcal{T}$  there exists an invariant measure  $\nu$  on Y such that  $(Y, \nu, S)$  is measure-theoretically isomorphic to  $(X, \mu, T)$ .

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Informally: The simplex of invariant measures of (Y, S) contains nothing but the isomorphic copies of measures of systems from T.

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PROBLEM (Weiss): Find a universal model for the class of automorphisms of zero entropy, or more generally, for the class  $T = \{T : h(T) \le r\}$ , for  $r \ge 0$ .

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### Theorem

There does not exist a topological dynamical system, universal in the class of all automorphisms of entropy zero.

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- if U(n) 
   <sup>¬</sup>∞ is a sequence for which <sup>1</sup>/<sub>n</sub> log U(n) → 0 then there exists an ergodic zero-entropy system whose measure-theoretic complexity grows faster than U(n)

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#### Main result

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• For  $\epsilon > 0$ , the  $(\epsilon, n)$ - ball with center  $B \in \Lambda^n$  is:

$$\mathbb{B}_{\mathcal{H}}(\boldsymbol{B},\epsilon) = \bigcup_{\{\boldsymbol{C}\in\Lambda^n: d_{\mathcal{H}}(\boldsymbol{B},\boldsymbol{C})<\epsilon\}} [\boldsymbol{C}].$$

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A simple fact: if (Y, S) is a symbolic system with (symbolic) complexity U<sub>Y</sub>(n), ν is an S-invariant ergodic measure, P is a finite partition then clearly K<sub>ν</sub>(P, ε, n, S) ≤ U<sub>Y</sub>(n).

## Third ingredient again:

# Lemma (Rapidly growing complexity in entropy zero)

For every nondecreasing sequence U(n) of positive numbers such that  $\frac{1}{n} \log U(n) \rightarrow 0$ , there exists an ergodic measure-theoretic dynamical system  $(X, \mu, T)$  with  $h_{\mu}(T) = 0$ , and a finite measurable partition Q of X such that the measure-theoretic complexity of  $(X, \mu, T)$  with regard to Q is NOT dominated by U(n).

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- Clearly (VP)  $h_{top}(S') = 0$ .
- First ingredient: (Y', S') has a symbolic extension (Y, S) of zero entropy. Let (U<sub>Y</sub>(n))<sub>n≥1</sub> be the *symbolic complexity* of (Y, S).
- By the second ingredient, if ν is an S-invariant ergodic measure and P is a finite partition of Y, then the measure-theoretic complexity of (Y, ν, S) with respect to P is dominated by U<sub>Y</sub>(n).

As h<sub>top</sub>(S) = 0, we have <sup>1</sup>/<sub>n</sub> log U<sub>Y</sub>(n) → 0, so by the third ingredient, there exists an ergodic zero-entropy measure-preserving system (X, μ, T), and a finite partition Q of X, such that the measure-theoretic complexity of (X, μ, T) with regard to Q grows essentially faster than U<sub>Y</sub>(n).

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- In particular, the measure-theoretic complexity of (Y, ν, S) with regard to P is NOT dominated by U<sub>Y</sub>(n). This contradicts the existence of a universal zero-entropy system.

 Elements of X are arrays, rows 1, 2, ... contain an appropriate odometer.

To define the 0th row need two elementary operations.

If C is a collection of blocks of a fixed length and  $q \in \mathbb{N}$  then  $C^q$  is the family of all (independent) concatenations of q blocks from C. Also,  $C_{rep} = \{CC : C \in C\}$  is the collection of repetitions of blocks from C.

Clearly  $\operatorname{card}(\mathcal{C}_{\mathsf{rep}}) = \operatorname{card}(\mathcal{C})$  and  $\operatorname{card}(\mathcal{C}^q) = (\operatorname{card} \mathcal{C})^q$ .

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- A *k*-block of *x* is any block x<sub>0</sub>[n, n + N<sub>k</sub> − 1], where n is a position of a *k*-marker in x.
- We determine X by requiring that x ∈ X, if and only if, for any k, every k-block of x belongs to (B<sub>k</sub>)<sub>rep</sub>. In other words, x ∈ X if 0th row x<sub>0</sub> is, for every k, an infinite concatenation of the blocks from (B<sub>k</sub>)<sub>rep</sub> with "gluing points" at the k-markers.

X is nonempty, closed and shift-invariant, all blocks from B<sub>k</sub> (for every k) occur in the 0th row system X<sub>0</sub>.

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- Define an invariant measure on X: for each k ≥ 1, declare all k-blocks occurring in X to have the same measure:

$$\mu(\{x: x_0[0, N_k - 1] = BB, x_k(0) = 1\} = \frac{1}{N_k \cdot \operatorname{card}(\mathcal{B}_k)} = \frac{1}{N_k 2^{p_k}},$$

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• Verification that the above indeed determines a shift-invariant ergodic measure on X is standard. Variational principle implies that  $h_{\mu}(T) = 0$ .

• Let  $Q = \{[0], [1]\}$ , where  $[0] = \{x \in X : x_0(0) = 0\}$  and  $[1] = \{x \in X : x_0(0) = 1\}$ , be the zero-coordinate partition of the 0th row, lifted to X.

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- X splits into  $N_k$  sets  $P_0, P_1, P_2, \ldots, P_{N_k-1}$  of equal measure  $\frac{1}{N_k}$ , where  $P_i = \{x : x_k(i) = 1\}$ , for  $i = 0, \ldots, N_k 1$ , and  $k \ge 1$ .

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- The mechanism of concatenations and repetitions: the entries of a block B ∈ B<sub>k</sub> are determined by a subset of p<sub>k</sub> (out of N<sub>k</sub>/2) coordinates, making up a fraction <sup>1</sup>/<sub>2<sup>k</sup></sub> of the length of B. The symbols occurring along these coordinates are arbitrarily, each of them is then repeated 2<sup>k</sup> times in B.

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- We have a bijection  $\phi_k : \mathcal{B}_k \to \{0, 1\}^{p_k}$  such that:
  - $\phi_k$  is "distance-preserving", i.e.  $d_H(B, C) = d_H(\phi_k(B), \phi_k(C))$ ,
  - $\lambda(\phi_k(B)) = \mu(B|P_0) = 2^{-p_k}$ , where  $\lambda = \{\frac{1}{2}, \frac{1}{2}\}^{\mathbb{Z}}$ .

This bijection allows us to perform our estimation using the measure  $\lambda$ .

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(a)

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Notice that applying Stirling's formula we have

$$\operatorname{Card} \{ \boldsymbol{C} \in \{0,1\}^n : \boldsymbol{d}_{\boldsymbol{H}}(\boldsymbol{B},\boldsymbol{C}) < \delta \} = \sum_{j < \delta n} \binom{n}{j} \leq 2^{n H(2\delta)},$$

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Fix ε > 0. All 2<sup>n</sup> cylinders of length n have equal measure λ, so the minimal cardinality of a subfamily of cylinders whose elements cover up more than 1 − ε (in measure) of the space, must be at least (1 − ε) · 2<sup>n</sup>. All (δ, n)-Hamming balls include the same number of cylinders, so we have

$$M(\delta, n, \epsilon) \ge \frac{(1-\epsilon) \cdot 2^n}{2^{nH(2\delta)}} = (1-\epsilon)2^{n(1-H(2\delta))}$$
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• Using the above we can estimate from below the quantity  $K_{\mu}(Q, \epsilon, N_k, T)$ .