

# Arnold diffusion in the restricted planar three body problem

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# The restricted planar three body problem (RP3BP)

- We consider the motion of three bodies  $q_1$ ,  $q_2$  and  $q$ , of masses  $m_1$ ,  $m_2$ , and 0 under the effects of the Newtonian gravitational force. Usually one works with the mass ratio  $\mu = \frac{m_2}{m_1+m_2}$ ,  $m_1 \geq m_2$ , and one considers the masses  $1 - \mu$ ,  $\mu$  ( $0 \leq \mu \leq 1/2$ ) and 0.
- The bodies with mass (**primaries**)  $q_1$ ,  $q_2$  are not influenced by the massless one  $q$ .
- $q_1$  and  $q_2$  form a two body problem. Therefore their motion is governed by Kepler laws.
- We will assume the two primaries  $q_1$ ,  $q_2$  move on ellipses (**elliptic case**): a particular case is when they move in circles (**circular case**)
- Goal: understand the motion of the massless body  $q$  under the influence of the other two.

# The restricted planar three body problem (RP3BP)

The particle  $q$  with zero mass moves under the effects of the Newtonian gravitational force exerted by the two **primaries**  $q_1$  and  $q_2$  of **masses**  $1 - \mu$  and  $\mu$  evolving in **elliptic** orbits around their center of mass. The circular case is a particular case of the elliptic one, where the primaries move in elliptic orbits.

Typical models in the elliptic case with eccentricity  $e_0$ :

- Sun–Jupiter–asteroid or comet:  $e_0 = 0.048$
- Sun–Earth–Moon systems:  $e_0 = 0.016$

# The equations of the RP3BP

- The motion of the massless particle  $q = (q^1, q^2) \in \mathbb{R}^2$  (planar problem) is described by Newton laws. After normalizing:

$$\frac{d^2 q}{dt^2} = \frac{(1 - \mu)(q_1(t) - q)}{\|q_1(t) - q\|^3} + \frac{\mu(q_2(t) - q)}{\|q_2(t) - q\|^3},$$

where  $q_1(t)$ ,  $q_2(t)$  are the position of the primaries, which move in an elliptic orbit of excentricity  $e_0$ .

- This is a  $2\pi$ -periodic in time Hamiltonian system (2 and 1/2 degrees of freedom) with Hamiltonian

$$\mathcal{H}(q, p, t; \mu, e_0) = \frac{p^2}{2} - \frac{(1 - \mu)}{|q - q_1(t)|} - \frac{\mu}{|q - q_2(t)|}.$$

$p = (p^1, p^2) = \frac{dq}{dt}$ ,  $q = (q^1, q^2)$ .

- Parameters:  $0 < e_0 < 1$  the excentricity of the ellipse ( $q_1(t)$  and  $q_2(t)$  depend on  $e_0$ ) and  $\mu \in [0, 1/2]$ .

# The equations of the RP3BP

- In the elliptic case  $e_0 > 0$ , one has:

$$q_1(t) = -\mu r_0(t)q_0(t), \quad q_2(t) = (1 - \mu)r_0(t)q_0(t)$$

where

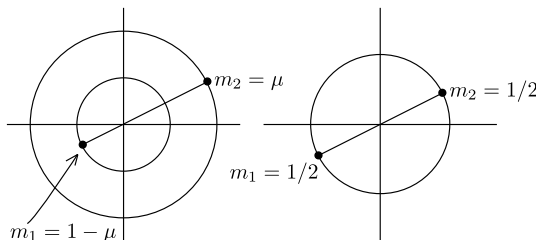
$$r_0 = r_0(t; e_0) = \frac{1 - e_0^2}{1 + e_0 \cos f(t)}, \quad \frac{df}{dt} = \frac{(1 + e_0 \cos f)^2}{(1 - e_0^2)^{3/2}}.$$

and  $f(t) = f(t; e_0)$  is the **true anomaly**, and

$$q_0(t) = (\cos f(t), \sin f(t))$$

- In the circular case  $e_0 = 0$ , one has:  $q_1(t) = -\mu q_0(t)$ ,  $q_2(t) = (1 - \mu)q_0(t)$  and  $q_0(t) = (\cos t, \sin t)$  correspond to the circular motion of the primaries.

Motion of the primaries in the **circular case**:  $e_0 = 0$



- In general, the Hamiltonian is  $2\pi$ -periodic in time, therefore it is NOT a first integral of the problem.
- The RPC3BP has a first integral called **Jacobi constant**

$$\mathcal{J}(q, p, t; \mu) = \mathcal{H}(q, p, t; \mu, 0) - (q_1 p_2 - q_2 p_1).$$

## Circular RP3BP in rotating polar coordinates

When  $e_0 = 0$ , we can make some classical changes of variables to simplify the Hamiltonian:

- Fix the primaries at the  $x$  axis taking a reference system which moves periodically with time (periodic in time change of variables): **sinodic coordinates**

$$q_1 = (\mu, 0), \quad q_2 = (1 - \mu, 0).$$

- Polar coordinates for the third body:  $q = (r \cos \phi, r \sin \phi)$ .
  - $y$  symplectic conjugate to  $r$  (radial velocity).
  - $G$  symplectic conjugate to  $\phi$  (angular momentum).
- We get an **autonomous Hamiltonian of two degrees of freedom**:

$$H(r, \phi, y, G; \mu) = \frac{y^2}{2} + \frac{G^2}{2r^2} - G - U(r, \phi; \mu),$$

- $U(r, \phi; \mu)$  is the Newtonian potential, which satisfies  $U(r, \phi; \mu) \simeq \frac{1}{r}$ .
- $H$  is a first integral (Is the Jacobi constant  $\mathcal{J}$ ).

## Elliptic RP3BP in rotating polar coordinates

If we perform the same changes of variables in the elliptic case (remember that there is no an extra first integral in this case):

We get an non-autonomous Hamiltonian:

$$H(r, \phi, y, G, t; \mu, e_0) = \frac{y^2}{2} + \frac{G^2}{2r^2} - G - U(r, \phi, t; \mu, e_0),$$

$U(r, \phi, t; \mu, e_0)$  also satisfies  $U(r, \phi, t; \mu, e_0) \simeq \frac{1}{r}$ .

The system has two and a half degrees of freedom.

We will work in the extended phase space:

$$((r, \phi, y, G, s) \in \mathbb{R} \times \mathbb{T} \times \mathbb{R}^2 \times \mathbb{T}$$

$$H(r, \phi, y, G, s; \mu, e_0) = \frac{y^2}{2} + \frac{G^2}{2r^2} - G - U(r, \phi, s; \mu, e_0),$$

and  $\dot{s} = 1$



Limiting case  $\mu \rightarrow 0$ 

For  $\mu = 0$  and for any  $e_0$ :

- The massless body  $q$  is only influenced by one body  $q_1$  ( $q_2$  has also zero mass!).
- Its motion is governed by Kepler laws (the central force problem).
- It moves on conic sections.

Limiting case  $\mu \rightarrow 0$ 

For  $\mu = 0$  and for any  $e_0$ :

- As  $U(r, \phi, s; 0, e_0) = \frac{1}{r}$ , the Hamiltonian for  $\mu = 0$ , becomes, both in the elliptic and circular case:

$$H(r, \phi, y, G, s; 0, e_0) = H_0(r, y, G) - G = \frac{y^2}{2} + \frac{G^2}{2r^2} - \frac{1}{r} - G,$$

$h = H_0$  is the energy.

- Possible types of motion:
  - $H^\pm$  (hyperbolic): motion on hyperbolas:  $h > 0$
  - $P^\pm$  (parabolic): motion on parabolas:  $h = 0$
  - $B^\pm$  (bounded): motion on ellipses  $h < 0$
- The angular momentum  $G$  is preserved.

## Purposes for $\mu > 0$

We want to see:

- There is another possible type of motion: **Oscillatory motion** :

$$\limsup_{t \rightarrow \pm\infty} \|q\| = +\infty \quad \text{and} \quad \liminf_{t \rightarrow \pm\infty} \|q\| < +\infty$$

Proved for any  $0 < \mu \leq 1/2$  (Guardia-Martin-S) and  $e_0 = 0$  in:  
**Oscillatory motions for the restricted planar circular three body problem**

Preprint at

<http://arxiv.org/abs/1207.6531>

Future project  $e_0 > 0$ .

- For  $e_0 > 0$ , the angular momentum  $G$  can have changes of  $O(1)$  even if  $\mu$  is very small: **Arnold diffusion**

## $\mu > 0$ , The elliptic case: Increasing the angular momentum

Final goal: in the elliptic restricted three body (ERTBP) problem we want to see that the angular momentum of the third body  $G(t)$  can have *large changes*

We have partial results when the eccentricity  $e_0 > 0$  and  $\mu > 0$  are small enough:

Given any  $G_1, G_2 \gg 1$ , there exist heteroclinic trajectories of the ERTBP whose angular momentum satisfies, for some  $T > 0$ :

$$G(0) < G_1 \quad G(T) > G_2$$

Proven for  $0 < \mu \ll e_0 \ll 1$  and any  $1 \ll G_1, G_2 \leq 1/e_0$ .

## Previous results for oscillatory motions or diffusion close to parabolic orbits

- Sitnikov 1960 (later Moser) considered the restricted spatial elliptic three body problem with a specific configuration.
- Llibre-Simó 1980 (oscillatory motions in the RPC3BP for  $0 < \mu \ll 1$ )
- Moeckel 1984: extended the result of Sitnikov to the case of three bodies with positive masses, two of them equal, in an isosceles configuration.
- Xia 1992 ( for RPC3BP oscillatory motions for every  $\mu \in (0, 1/2]$  except a finite number of values)
- Galante-Kaloshin 2011( orbits initially bounded and which become oscillatory:  $\mu = 10^{-3}$ , realistic for the Jupiter-Sun)
- Kaloshin and Gorodetski 2011 (results about the Hausdorff dimension of oscillatory motions for both the Sitnikov problem and the RPC3BP)
- Xia 1993 (local diffusion in the ERTBP)
- **Martínez-Pinyol 1994** (Massive computations in the ERTBP)

## Previous results: other types of oscillatory motions or diffusion:

- Llibre-Martínez-Simó 1985 (oscillatory motions close to  $L_2$  in the CRTBP)
- Bolotin 2006 (close to collision in the ERTBP)
- Capiński-Zgliczyński 2011 (close to  $L_2$  in the ERTBP)
- Féjoz-Guàrdia-Kaloshin-Roldán 2012 (close to resonances in the ERTBP)

## Limiting case $\mu \rightarrow 0$ : Infinity

- Equations

$$\begin{aligned}\dot{r} &= y \\ \dot{y} &= \frac{G^2}{r^3} - \frac{1}{r^2} \\ \dot{\phi} &= -1 + \frac{G}{r^2} \\ \dot{G} &= 0 \\ \dot{s} &= 1\end{aligned}$$

- For any value of  $(\phi_0, G_0, s_0)$ , the “infinity”:

$$(r, y, \phi, G, s) = (\infty, 0, \phi_0 - t, G_0, s_0 + t), t \in \mathbb{T}$$

is a periodic solution.

- At infinity,  $H$  coincides with angular momentum:

$$H(\infty, \phi, 0, G_0, s; 0, e_0) = -G_0.$$

Limiting case  $\mu \rightarrow 0$ : McGehee coordinates

$x^2 := 1/r$ : Gives a better geometrical understanding of the problem



$$\dot{x} = -\frac{x^3}{2} \frac{\partial K_0}{\partial y}$$

$$\dot{y} = \frac{x^3}{2} \frac{\partial K_0}{\partial x}$$

$$\dot{\phi} = \frac{\partial K_0}{\partial G} - 1$$

$$\dot{G} = 0$$

$$\dot{s} = 1$$

- $K_0(x, y, G) = H_0(\frac{1}{x^2}, y, G) = \frac{y^2}{2} + \frac{G^2 x^4}{2} - x^2$ , is a first intergral.

- For any value of  $(\phi_0, G_0, s_0)$ :

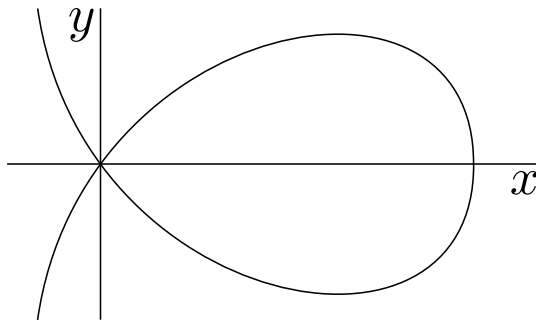
$\Lambda_{\phi_0, G_0, s_0} = \{(x, y, \phi, G, s) = (0, 0, \phi_0 - t, G_0, s_0 + t), t \in \mathbb{T}\}$  is a periodic solution.



## Limiting case $\mu \rightarrow 0$ : McGehee coordinates

**Homoclinic manifold:** For any fixed  $G_0$ , in the  $(x, y)$  plane;  $(0, 0)$  is a (parabolic) critical point which has the separatrix loop

$$\gamma_{G_0} = \{K_0(x, y, G_0) = 0\}.$$



In the whole extended phase space this will give rise to an homoclinic manifold  $\gamma_{\phi_0, G_0, s_0}$  to the periodic orbit  $\Lambda_{\phi_0, G_0, s_0}$

# Limiting case $\mu \rightarrow 0$ : A priori unstable structure, inner dynamics

Main features we will use:

- The 3 dimensional manifold:

$$\Lambda_\infty = \{x = y = 0, (\phi, G, s) \in \mathbb{T} \times \mathbb{R}_+ \times \mathbb{T}\}$$

is invariant.

- $\Lambda_\infty = \bigcup_{\phi, G, s} \Lambda_{\phi, G, s}$ , being  $\Lambda_{\phi, G, s}$  periodic orbits.
- The inner dynamics on  $\Lambda_\infty$  is trivial:

$$(\phi, G, s) \rightarrow (\phi - t, G, s + t)$$

- $\Lambda_\infty$  has stable and unstable manifolds.

# Limiting case $\mu \rightarrow 0$ : A priori unstable structure, outer dynamics

An invariant 4-dimensional homoclinic manifold to  $\Lambda_\infty$ .

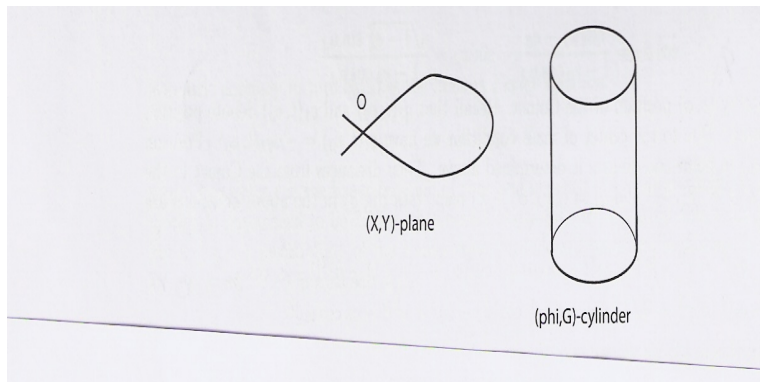
$$\begin{aligned}\gamma &= W_0^s(\Lambda_\infty) = W_0^u(\Lambda_\infty) \\ &= \{K_0(x, y, G) = 0, (\phi, G, s) \in \mathbb{T} \times \mathbb{R}_+ \times \mathbb{T}\}\end{aligned}$$

This makes  $\Lambda_\infty$  a normally parabolic invariant manifold

$\gamma$  can be seen as a union of **parabolic homoclinic** orbits to  $\Lambda_{\phi, G, s}$ .

$$\gamma = \bigcup_{(\phi, G, s)} \gamma_{\phi, G, s}$$

# Limiting case $\mu \rightarrow 0$ : A priori unstable structure, outer dynamics



We can parameterize the homoclinic manifold as:

$$\gamma = \{z := (x_G(\tau), y_G(\tau), \phi_G(\tau) + \phi, G, s), \tau \in \mathbb{R}, G \in \mathbb{R}_+, (\phi, s) \in \mathbb{T}^2\}$$

## Limiting case $\mu \rightarrow 0$ : A priori unstable structure, outer dynamics

We can define the scattering map (Delshams-Llave-S. 2000) in  $\Lambda_\infty$ . Its is associated to the homoclinic manifold  $\gamma$

$$S_0 : \Lambda_\infty \rightarrow \Lambda_\infty$$

by  $z_+ = S_0(z_-)$  iff  $\exists z \in \gamma$  such that

$$d(\varphi(t; z), \varphi(t; z_\pm)) \rightarrow 0 \text{ as } t \rightarrow \pm\infty.$$

The orbit through  $z$  is a heteroclinic connection between the orbits through  $z_\pm \in \Lambda_\infty$ .

# Limiting case $\mu \rightarrow 0$ : A priori unstable structure, outer dynamics

Using the point of  $z \in \Gamma$  given by:

$$z = (x_G(\tau), y_G(\tau), \phi_G(\tau) + \phi, G, s)$$

one can compute  $S_0$  in coordinates:

$$S_0(\phi, G, s) = (\phi, G, s)$$

As  $S_0 = Id$ , the unperturbed periodic orbits  $\Lambda_{\phi, G, s}$  only have homoclinic connections.

Dynamics of infinity for  $\mu > 0$ 

In McGehee variables  $(x, y, \phi, G, s)$ , the Hamiltonian is:

$$K(x, y, \phi, G, s; \mu, e_0) = \frac{y^2}{2} + \frac{G^2 x^4}{2} - V(x, \phi, s; \mu, e_0)$$

with  $V(x, \phi, s; \mu, e_0) = x^2 \tilde{V}(x, \phi, s; \mu, e_0)$

Implications:

- $\Lambda_\infty = \{x = y = 0, (\phi, G, s) \in \mathbb{T} \times \mathbb{R}_+ \times \mathbb{T}\}$  is still invariant.
- The periodic orbits  $\Lambda_{\phi, G, s}$  persist.
- The inner dynamics on  $\Lambda_\infty$  is still trivial:

$$(\phi, G, s) \rightarrow (\phi - t, G, s + t)$$

$\mu > 0$ : The elliptic case: increasing the angular momentum

## Main goal:

- For  $\mu > 0$  (and  $e_0 > 0$ ) we want to see that we that the stable and unstable manifolds of  $\Lambda_\infty$  intersect transversally.
- For  $\mu > 0$  (and  $e_0 > 0$ ) we want to see that we that the unstable manifold of the periodic orbits  $\Lambda_{\phi_1, G_1, s}$  intersect transversally the stable manifold of other periodic orbit  $\Lambda_{\phi_2, G_2, s}$  with  $G_2 > G_1$ .

Equivalently:

For  $\mu > 0$  (and  $e_0 > 0$ ) we want to see that we can define a scattering map in  $\Lambda_\infty$  such that the image of one periodic orbit intersects other periodic orbits with larger angular momentum  $G$ :

$$S_\mu(\Lambda_{\phi_1, G_1, s}) \cap \Lambda_{\phi_2, G_2, s} \neq \emptyset$$

with  $G_2 > G_1$ .

Then we will have **heteroclinic connections between periodic orbits**.



$\mu > 0$ , The elliptic case: increasing the angular momentum

Remember the Hamiltonian in the elliptic case is NOT autonomous:

$$H(r, \phi, y, G, s; \mu, e_0) = \frac{y^2}{2} + \frac{G^2}{2r^2} - G - U(r, \phi, s; \mu, e_0),$$

The phase space is 5 dimensional.

For  $\mu > 0$  (and  $e_0 > 0$ ) it is possible to have heteroclinic connections between periodic orbits with different angular momentum.

$\mu > 0$ , The circular case  $e_0 = 0$ 

In the circular case the Hamiltonian is autonomous:

$$H(r, \phi, y, G; \mu, 0) = \frac{y^2}{2} + \frac{G^2}{2r^2} - G - U(r, \phi; \mu, 0)$$

The energy of  $\Lambda_{\phi, G, s}$  is  $H = -G$ .

As the energy is preserved heteroclinic orbits between periodic orbits with different angular momentum are not possible!

Arnold diffusion is not possible but the transversal intersection between the invariant manifolds of  $\Lambda_\infty$  will give rise to another important phenomenon: **The existence of oscillatory motions.**

# The invariant manifolds of $\Lambda_\infty$ for $e_0 > 0$ , $\mu > 0$ : Melnikov approach

For  $\mu > 0$ , we want to see that the manifolds  $W_\mu^s(\Lambda_\infty)$  and  $W_\mu^u(\Lambda_\infty)$  intersect transversally.

This result is based on a Melnikov type computation (see A. de la Rosa's talk)

Classical Melnikov potential:

$$\mathcal{L}(\phi, G, s; e_0) = \int_{-\infty}^{\infty} \overline{\Delta V}(x_G(t), \phi_G(t) + \phi, s + t; e_0) dt.$$

where  $V(x, \phi, s; \mu, e_0) = x^2 + \mu \overline{\Delta V}(x, \phi, s; e_0) + O(\mu^2)$

**Intersection property:** If the function

$$\tau \mapsto \mathcal{L}(\phi, G, s - \tau; e_0)$$

has a *non-degenerate critical point*  $\tau^*(\phi, G, s; e_0)$ , then there is a transversal intersection between  $W^u(\tilde{\Lambda}_\infty)$  and  $W^s(\tilde{\Lambda}_\infty)$  close to  $\tilde{z}_0 = (x_G(\tau^*), y_G(\tau^*), \phi_G(\tau^*) + \phi, G, s)$ .

## The invariant manifolds of $\tilde{\Lambda}_\infty$ for $e_0 > 0$ , $\mu > 0$ : the reduced Poincaré function

For any fixed  $(\phi, G, e_0)$ , we just need to find a non-degenerate critical point  $s^*(\phi, G; e_0)$  of  $s \mapsto \mathcal{L}(\phi, G, s; e_0)$ , that is, a solution  $s^*(\phi, G; e_0)$  of the equation

$$\frac{\partial \mathcal{L}}{\partial s}(\phi, G, s; e_0) = 0, \quad \frac{\partial^2 \mathcal{L}}{\partial s^2}(\phi, G, s; e_0) \neq 0$$

and we recover  $\tau^*(\phi, G, s; e_0) = s - s^*(\phi, G; e_0)$

Once we have  $\tau^*(\phi, G, s; e_0)$  we can consider the *reduced Poincaré function*

$$\mathcal{L}^*(\phi, G; e_0) = \mathcal{L}(\phi, G, s - \tau^*(\phi, G, 0; e_0); e_0) = \mathcal{L}(\phi, G, s^*(\phi, G; e_0); e_0)$$

# The scattering map for $e_0 > 0$ , $\mu > 0$

The scattering map  $S$  given by the homoclinic intersection associated to the critical point  $s^*(\phi, G; e_0)$  is given as:

$$(\phi, G, s) \mapsto \left( \phi - \mu \frac{\partial \mathcal{L}^*}{\partial G}(\phi, G; e_0) + O(\mu^2), G + \mu \frac{\partial \mathcal{L}^*}{\partial \phi}(\phi, G; e_0) + O(\mu^2), s \right)$$

$S$  is given, up to first order in  $\mu$ , as the **time  $-\mu$  Hamiltonian flow of the autonomous Hamiltonian  $\mathcal{L}^*(\phi, G; e_0)$** !

Then, looking at the level curves of  $\mathcal{L}^*(\phi, G; e_0)$  we get the images under the scattering map.

# The scattering map for $e_0 > 0, \mu > 0$

The inner dynamics in  $\tilde{\Lambda}_\infty$  is trivial:

$$(\phi, G, s) \mapsto (\phi, G, s + t)$$

The classical geometric mechanism to obtain diffusion does not work: there is no possibility of combining the inner and the outer dynamics to obtain large changes of  $G$ .

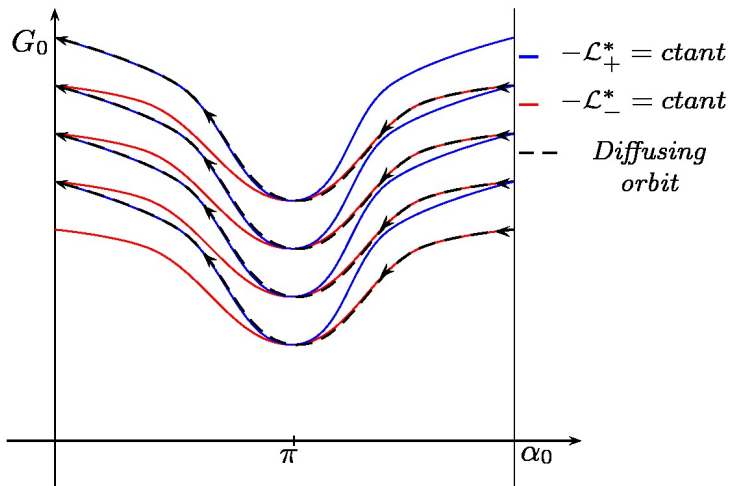
The time  $2\pi$ -Poincaré map  $P(\phi, G, s) = (\phi, G, s)$ , therefore  $S \circ P = S$   
 Only with one scattering map we cannot get large changes in  $G$ .

## Combining two scattering maps for $\epsilon_0 > 0$ , $\mu > 0$

One can see that the function  $\mathcal{L}(\phi, G, s; \epsilon_0)$  has two non-degenerate critical points  $s_{\pm}^*(\phi, G; \epsilon_0)$  which give rise to two different reduced Poincaré functions  $\mathcal{L}_{\pm}^*$ . The scattering maps  $S_{\pm}$  are given by

$$(\phi, G) \mapsto \left( \phi - \mu \frac{\partial \mathcal{L}_{\pm}^*}{\partial G}(\phi, G; \epsilon_0) + O(\mu^2), G + \mu \frac{\partial \mathcal{L}_{\pm}^*}{\partial \phi}(\phi, G; \epsilon_0) + O(\mu^2) \right).$$

- $S_{\pm}$  are given, except for  $O(\mu^2)$ , as the time  $\mu$  Hamiltonian flow of the autonomous Hamiltonians  $-\mathcal{L}_{\pm}^*(\phi, G)$ .
- The iterates under  $S_{\pm}$  follow closely the level curves of  $\mathcal{L}_{\pm}^*$ .
- One can see that  $\{\mathcal{L}_{+}^*, \mathcal{L}_{-}^*\}$  only vanishes on  $\phi = 0, \pi$ , therefore, we can choose alternatively  $S_{\pm}$  to get diffusing pseudo-orbits and get diffusion along  $1 \ll G \leq 1/\epsilon_0$ .





The foliations of their level curves are transversal.

We can construct heteroclinic chains of periodic orbits with increasing angular momentum choosing the right scattering map any time

# Computation of the Melnikov potential $\mathcal{L}$ for $e_0 G \ll 1$ and big $G$

Computation of the Melnikov potential is delicate.

We have rigorous computations and bounds of the errors for  $e_0 G \leq 1$ .

Main idea:

- $\mathcal{L}$  is periodic in  $s$  and  $\phi$ .
- The  $k$ -th Fourier coefficient in the angle  $s$  is of order  $O(e^{-k\frac{G^3}{3}})$ .  
This is difficult to prove.
- One needs to compute the asymptotic of the first Fourier coefficients and bound the rest.

Arnold diffusion:  $e_0 > 0$ ,  $\mu > 0$ 

- We have rigorous results for the existence of heteroclinic orbits with increasing angular momentum if  $e_0 G \leq 1$  and  $\mu e^{\frac{G^3}{3}} \lll 1$
- A rigorous  $\lambda$ -lemma is needed to get true orbits.

How can improve the range of the parameters with the same results?

- A priori chaotic: In a recent work (Guardia-Martin-S) we have proved that  $W^u(\tilde{\Lambda}_\infty)$  and  $W^s(\tilde{\Lambda}_\infty)$  intersect transversally for  $e_0 = 0$ . Then, the circular restricted three body problem becomes a priori chaotic for any value of  $\mu$ , and we get results for  $|e_0 e^{\frac{G^3}{3}}| \lll 1$

Arnold diffusion:  $e_0 > 0$ , any  $\mu > 0$ 

One can see that this problem is a perturbation of the two body problem without assuming  $\mu$  small, nor  $e_0$  small.

Take  $\varepsilon$  small and perform the following changes of variables

$$r = \frac{1}{\varepsilon^2} \tilde{r}, \quad y = \varepsilon \tilde{y}, \quad \alpha = \tilde{\alpha} \quad \text{and} \quad G = \frac{1}{\varepsilon} \tilde{G}$$

and we rescale time as

$$t = \frac{1}{\varepsilon^3} s.$$

The rescaled system is Hamiltonian with respect

$$\tilde{H}(\tilde{r}, \tilde{y}, \alpha, \tilde{G}, \frac{s}{\varepsilon^3}; \mu, e_0) = \frac{\tilde{y}^2}{2} + \frac{\tilde{G}^2}{2\tilde{r}^2} - \tilde{V}(\tilde{r}, \alpha, \frac{s}{\varepsilon^3}; \varepsilon, e_0, \mu),$$

# The equations in scaled variables for small $\varepsilon$

where

$$\begin{aligned} \tilde{V}(\tilde{r}, \alpha, \frac{s}{\varepsilon^3}; \varepsilon, e_0, \mu) &= \frac{1-\mu}{(\tilde{r}^2 - 2(\mu\varepsilon^2)\tilde{r} \cos \alpha + (\mu\varepsilon^2)^2)^{1/2}} \\ &+ \frac{\mu}{(\tilde{r}^2 + 2((1-\mu)\varepsilon^2)\tilde{r} \cos \alpha + ((1-\mu)\varepsilon^2)^2)^{1/2}}. \end{aligned}$$

where  $\alpha = \phi + f(t_0 + \frac{s}{\varepsilon^3}; e_0)$ .

Note that, for any  $\mu$ , and  $e_0$ ,  $\tilde{V} = \frac{1}{r} + O(\varepsilon^2)$  and its dependence on time is through  $\phi = \phi + f(t_0 + \frac{s}{\varepsilon^3}; e_0)$ ,

In this way one can see:

- The exponentially small splitting comes from the fact that the **restricted three body problem is a small and fast perturbation of the two body problem for  $\varepsilon$  small and any  $e_0$  and  $\mu$ .**
- One can expect the diffusion phenomenon if we are able to deal with these exponentially small phenomena (done for  $e_0 = 0$ ).
- The first step will be the case  $e_0 G$  small without assumptions in  $\mu$