

Slow passage through bifurcations by PWL systems

A.E. Teruel



- A. PÉREZ, A.E.T. "*Slow passage through a transcritical bifurcation by PWL system*" WP
- J. PENALVA, M. DESROCHES, A.E.T., C. VICH "*Slow passage through a homoclinic loop in a PWL version of the Morris-Lecar model*" WP
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Slow passage phenomenon

- ▶ Given a 1-parameter ODE,

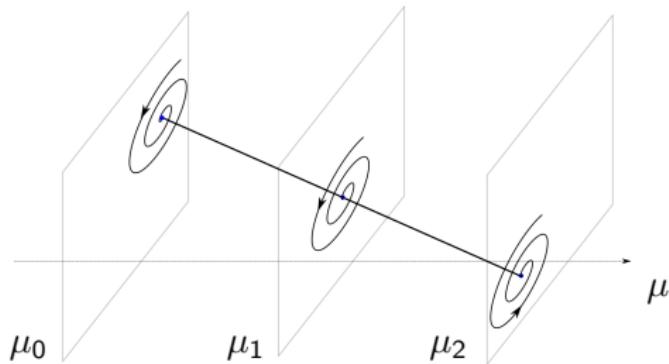
$$\dot{\mathbf{x}} = \mathbf{F}(\mathbf{x}, \mu)$$

consider slow dynamics for the parameter μ with $0 < \varepsilon \ll 1$.

- ▶ Fast subsystem ($\varepsilon = 0$), hence μ is constant.
- ▶ It is expected the understanding of the full flow, from that of the fast subsystem.

$$\dot{\mathbf{x}} = \mathbf{F}(\mathbf{x}, \mu)$$

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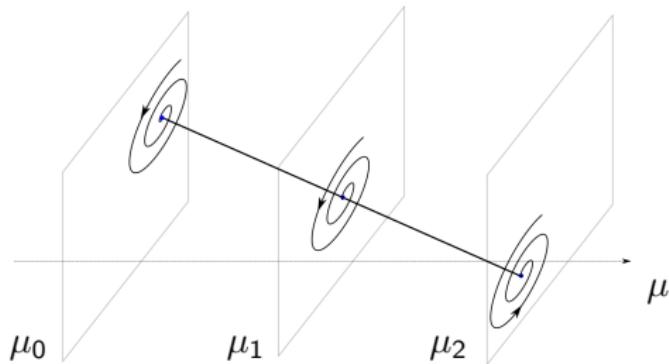
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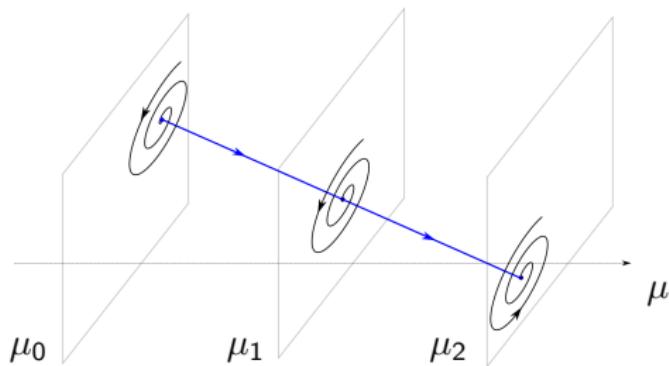
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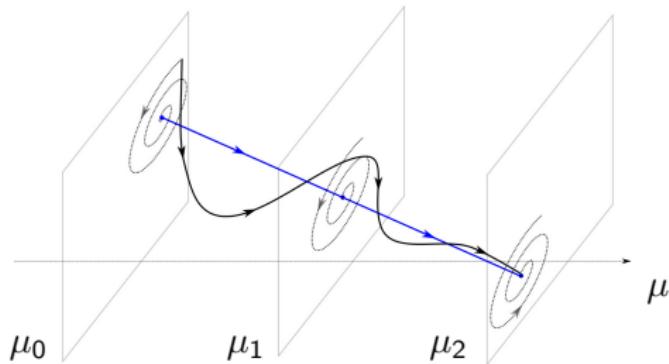
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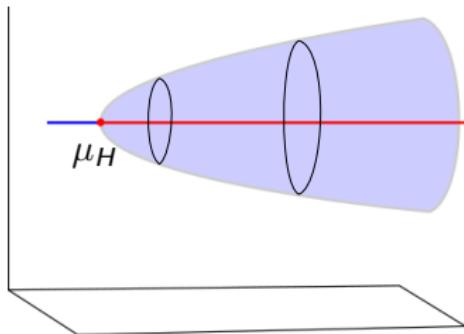
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Slow passage phenomenon

- ▶ Nevertheless, some unpredictable behaviours can appear when the fast subsystem undergoes a bifurcation.
- ▶ Slow passage through a supercritical Hopf bifurcation.



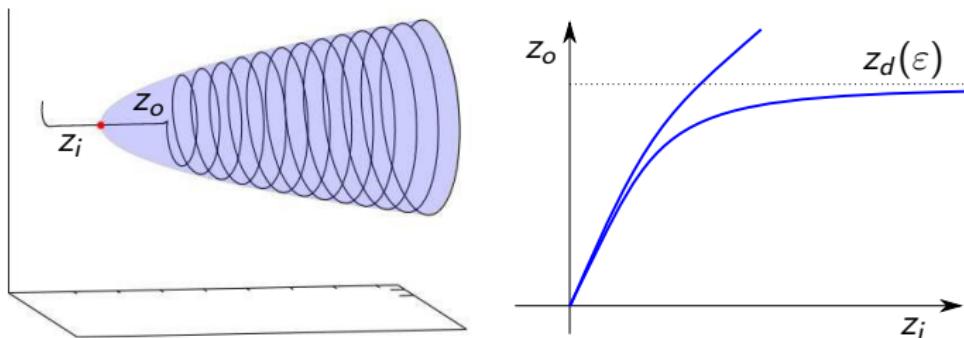
- ▶ Maximal delay $z_d(\varepsilon)$: depends on regularity of \mathbf{F}

$$\lim_{\varepsilon \searrow 0} z_d(\varepsilon) = 0; \quad z_d(\varepsilon) \text{ unbounded, } \forall \varepsilon; \quad \lim_{\varepsilon \searrow 0} z_d(\varepsilon) = C.$$

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Slow passage through a transcritical bifurcation

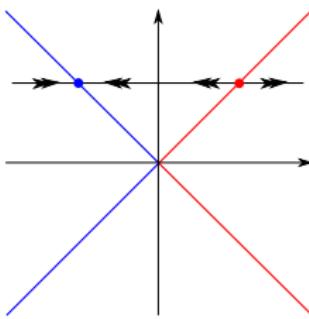
- ▶ In A. PÉREZ,A.E.T: "*Slow passage through a transcritical bifurcation by PWL systems*" work in progress.
- ▶ We revisit the transcritical scenario, where y is the bif. parameter.

$$\begin{aligned}\dot{x} &= x^2 - y^2 + \varepsilon\lambda, \\ \dot{y} &= \varepsilon.\end{aligned}$$

presented in: M. KRUPA, P SZMOLYAN, "*Extending slow manifolds near transcritical and pitchfork singularities*", Nonlinearity, 14, 2001.

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Slow passage through a transcritical bifurcation

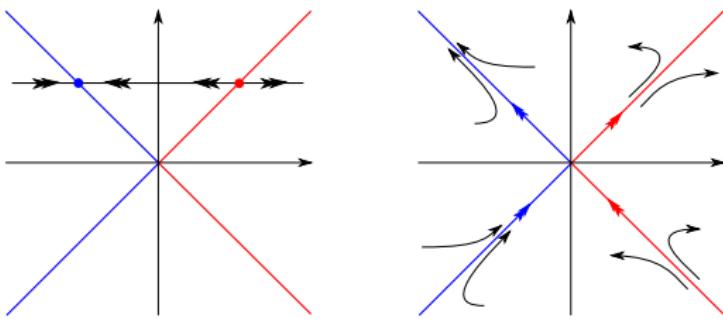
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Slow passage through a transcritical bifurcation

- ▶ Slow passage through a PWL transcritical bifurcation

$$\begin{aligned}\dot{x} &= |x| - |y| + \varepsilon\lambda, \\ \dot{y} &= \varepsilon\end{aligned}$$

Lipschitz vector field consisting of 4 four linear systems each defined in a quadrant.

- ▶ The first coordinate of the flow $\varphi(t; (x_0, y_0), \lambda, \varepsilon)$ is locally given by:

$$\varphi_1(t; (x_0, y_0), \lambda, \varepsilon) =$$

$$\begin{cases} (x_0 - y_0 + (\lambda - 1)\varepsilon)e^t + \varepsilon t + y_0 - (\lambda - 1)\varepsilon & (x_0, y_0) \in Q_1, \\ (x_0 + y_0 + (1 + \lambda)\varepsilon)e^t - \varepsilon t - y_0 - (\lambda + 1)\varepsilon & (x_0, y_0) \in Q_2, \\ (x_0 - y_0 + (1 - \lambda)\varepsilon)e^{-t} + \varepsilon t + y_0 + (\lambda - 1)\varepsilon & (x_0, y_0) \in Q_3, \\ (x_0 + y_0 - (1 + \lambda)\varepsilon)e^{-t} - \varepsilon t - y_0 + (\lambda + 1)\varepsilon & (x_0, y_0) \in Q_4, \end{cases}$$

- ▶ whereas the second one is

$$\varphi_2(t; (x_0, y_0), \lambda, \varepsilon) = y_0 + \varepsilon t.$$

Slow passage through a transcritical bifurcation

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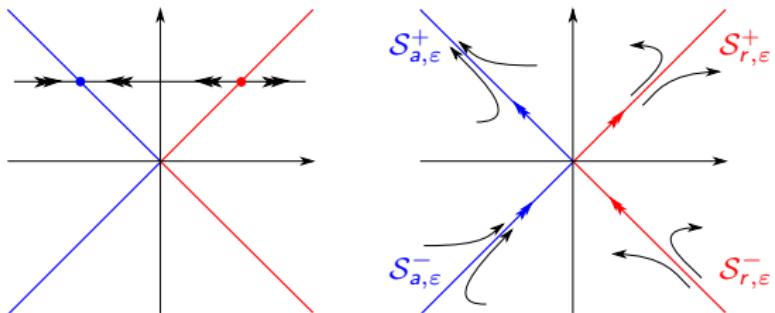
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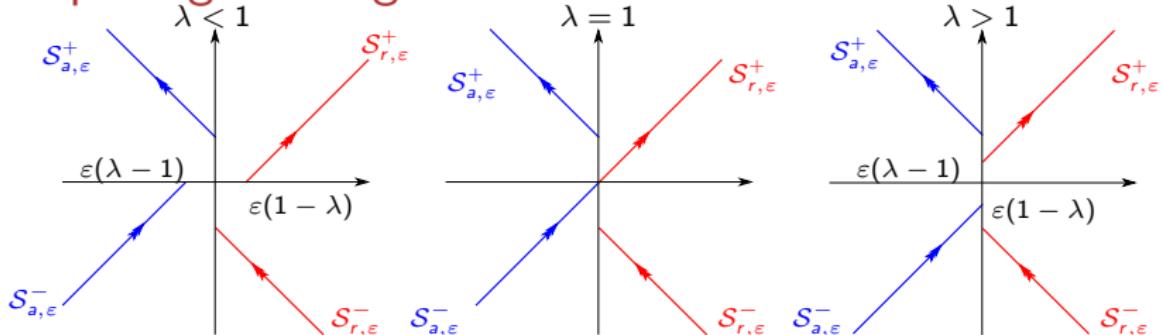
- ▶ Fast subsystem

$$\begin{aligned}\dot{x} &= |x| - |y|, \\ \dot{y} &= 0\end{aligned}$$



- ▶ $\mathcal{S}_{a,\varepsilon}^- = \{(x, y) : y = x + \varepsilon(1 - \lambda), \quad x < \min\{0, \varepsilon(\lambda - 1)\}\}$
- ▶ $\mathcal{S}_{a,\varepsilon}^+ = \{(x, y) : y = -x + \varepsilon(1 + \lambda), \quad x < 0\}$
- ▶ $\mathcal{S}_{r,\varepsilon}^- = \{(x, y) : y = -x - \varepsilon(1 + \lambda), \quad x < 0\}$
- ▶ $\mathcal{S}_{r,\varepsilon}^+ = \{(x, y) : y = x - \varepsilon(1 - \lambda), \quad x > \max\{0, \varepsilon(1 - \lambda)\}\}$

Slow passage through a transcritical bifurcation



$$\Delta^{in} = \{(-\rho, -\rho + \varepsilon(1 - \lambda) + \delta)\}$$

$$\xrightarrow{\Pi_a}$$

$$\Delta_a^{out} = \{(-\rho, \rho + \varepsilon(1 + \lambda) + \delta)\}$$

$$\xrightarrow{\Pi_e}$$

$$\Delta_e^{out} = \{(\rho, \delta)\}$$

Theorem: Fixed $\lambda > 0$, exists $\varepsilon_0(\lambda) > 0$ such that for $\varepsilon \in (0, \varepsilon_0(\lambda)]$.

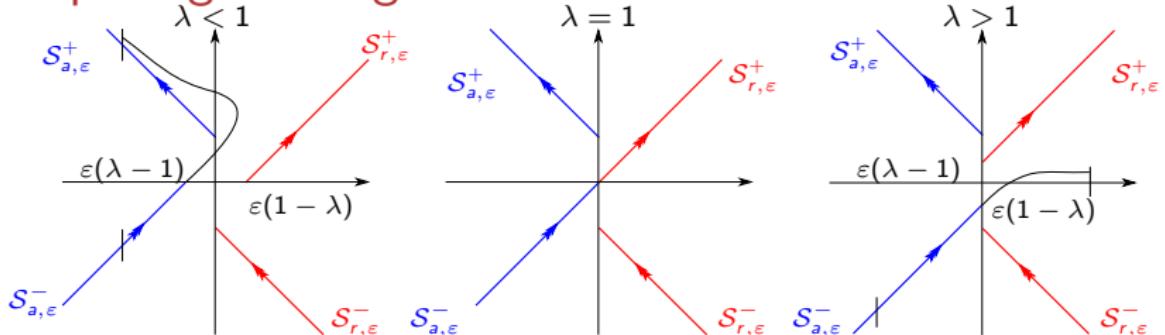
- a) If $\lambda > 1$: $S_{a,e}^-$ passes through Δ_e^{out} at $(\rho, h(\varepsilon))$ where $h(\varepsilon) = O(\varepsilon |\ln(\varepsilon)|)$. Π_a maps Δ^{in} to an interval containing $S_{a,e}^- \cap \Delta_e^{out}$ of size $O(e^{-c/\varepsilon})$.
- b) If $\lambda < 1$: Π_e maps Δ^{in} to an interval cont. $S_{a,e}^+ \cap \Delta_a^{out}$ of size $O(e^{-c/\varepsilon})$.

$$\varepsilon_0(\lambda) = \begin{cases} \frac{e^{1-C(\lambda)}}{C(\lambda)-1} & \lambda < 1, \\ \left(\frac{2(e^{\lambda-1}-1)}{\rho+\lambda-1}\right)^{\frac{1}{2}} & \lambda > 1, \end{cases}$$

where $\lim_{\lambda \rightarrow 1} C(\lambda) = +\infty$

and $\lim_{\lambda \rightarrow 1} \varepsilon_0(\lambda) = 0$.

Slow passage through a transcritical bifurcation



$$\Delta^{in} = \{(-\rho, -\rho + \varepsilon(1 - \lambda) + \delta)\}$$

$$\begin{array}{lcl} \xrightarrow{\Pi_a} & \Delta_a^{out} = \{(-\rho, \rho + \varepsilon(1 + \lambda) + \delta)\} \\ \xrightarrow{\Pi_e} & \Delta_e^{out} = \{(\rho, \delta)\} \end{array}$$

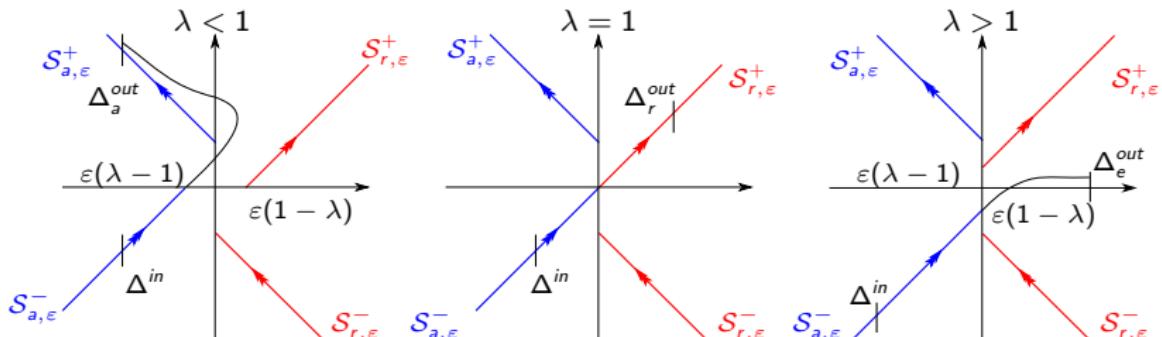
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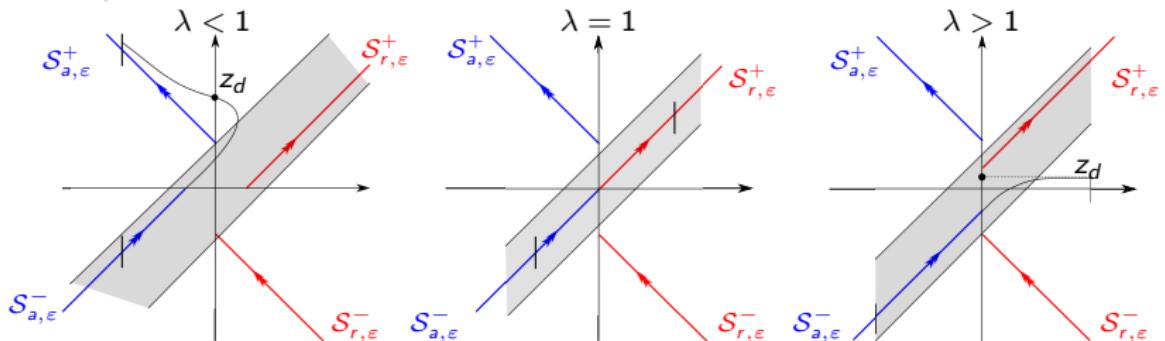
Slow passage through a transcritical bifurcation



$$\Delta^{in} = \{(-\rho, -\rho + \varepsilon(1 - \lambda) + \delta)\} \xrightarrow{\Pi_r} \Delta_r^{out} = \{(\rho - 2|r|, \rho - 2|r| + \delta)\}$$

Theorem: In the degenerate case $\lambda = 1$ transition map Π_r maps Δ^{in} to Δ_r^{out} .

Way-in/way-out function and maximal delay



Theorem: Fixed $\lambda > 0$.

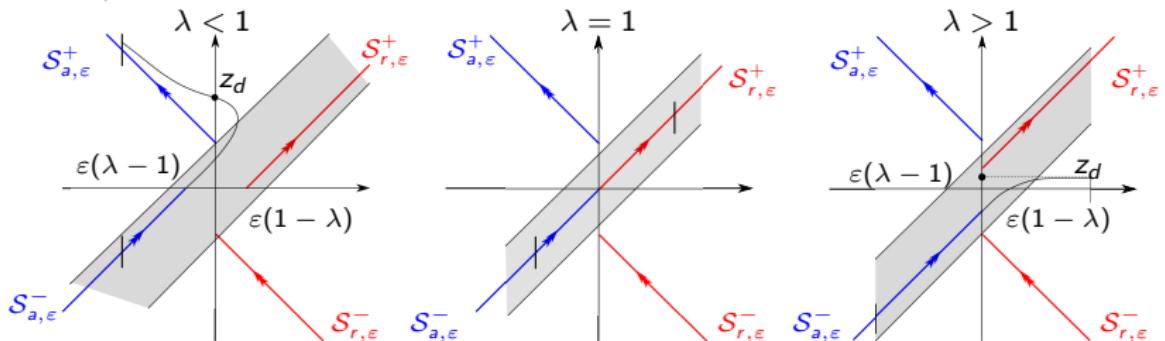
- a) If $\lambda > 1$, then maximal delay is $z_d(\varepsilon) = O(\varepsilon \ln(|\varepsilon|))$.
- b) If $\lambda < 1$, then maximal delay is $z_d(\varepsilon) = \varepsilon(\lambda + c)$ with $c \in (1, C(\lambda))$ where $C(\lambda)$ is a differentiable function satisfying:

$$C(\lambda) > 1, \quad C'(\lambda) > 0, \quad \lim_{\lambda \nearrow 1} C(\lambda) = +\infty, \quad \lim_{\lambda \nearrow 1} C'(\lambda) = +\infty.$$

- c) If $\lambda = 1$, then maximal delay is unbounded.

Maximal delay: Trivial behaviour.

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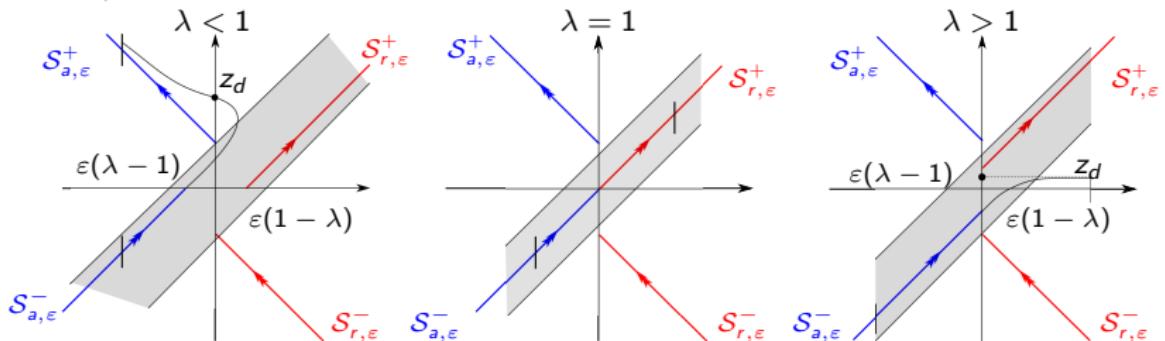
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Assuming $\lambda = 1 \pm e^{-\frac{c}{\varepsilon}}$ slow manifolds $S_{a,\varepsilon}^-$, $S_{r,\varepsilon}^+$ are exponentially close.

Theorem:

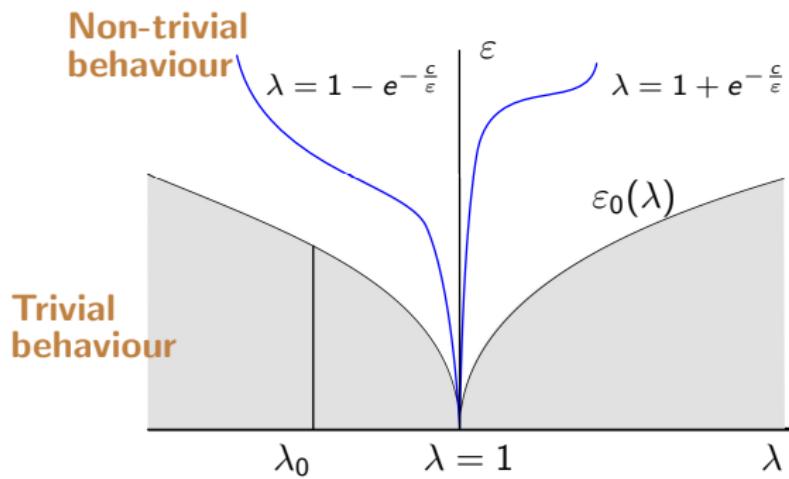
- If $\lambda = 1 - e^{-\frac{c}{\varepsilon}}$, then the maximal delay $z_d(\varepsilon) = c + \varepsilon h(\varepsilon)$ with $\lim_{\varepsilon \searrow 0} \varepsilon h(\varepsilon) = 0$.
- If $\lambda = 1 + e^{-\frac{c}{\varepsilon}}$, then the maximal delay $z_d(\varepsilon) = c + \varepsilon g(\varepsilon)$ with $\lim_{\varepsilon \searrow 0} \varepsilon g(\varepsilon) = 0$.

Maximal delay: Non trivial behaviour.

Way-in/way-out function and maximal delay

► Function $\varepsilon_0(\lambda) = \begin{cases} \frac{e^{1-C(\lambda)}}{C(\lambda)-1} & \lambda < 1, \\ \left(\frac{2(e^{\lambda-1}-1)}{\rho+\lambda-1} \right)^{\frac{1}{2}} & \lambda > 1, \end{cases}$

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