Reduction of chemical reaction networks

Sebastian Walcher, RWTH Aachen

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PART ONE: BACKGROUND AND MOTIVATION

A standard example: Michaelis-Menten

Chemical reaction network (CRN) with mass action kinetics:

$$E + S \stackrel{k_1}{\underset{k_{-1}}{\rightleftharpoons}} C \stackrel{k_2}{\rightharpoonup} E + P$$

Differential equation for concentrations by standard procedure:

$$\dot{s} = -k_1 e s + k_{-1} c,$$

 $\dot{c} = k_1 e s - (k_{-1} + k_2) c,$
 $\dot{e} = -k_1 e s + (k_{-1} + k_2) c,$
 $\dot{p} = k_2 c.$

Initial values $s(0) = s_0$, c(0) = 0, $e(0) = e_0$, p(0) = 0 and **stoichiometry** (linear first integrals e + c and s + c + p):

$$\dot{s} = -k_1 e_0 s + (k_1 s + k_{-1}) c,$$

 $\dot{c} = k_1 e_0 s - (k_1 s + k_{-1} + k_2) c.$

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QSS for Michaelis-Menten: Ancient history

Differential equation

Quasi-Steady State (QSS); Briggs and Haldane (1925): *QSS for complex C* means $\dot{c} = 0$; more precisely

$$0 = k_1 e_0 s - (k_1 s + k_{-1} + k_2) c \Longrightarrow c = \cdots$$

(Briggs and Haldane: Biochemical argument for QSS assumption, for small e_0 .)

Substitution into $\dot{s} = \cdots$ yields the **Michaelis-Menten equation**

$$\dot{s} = -rac{k_1k_2e_0s}{k_1s+k_{-1}+k_2}.$$

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QSS for Michaelis-Menten: More recent history

Heineken, Tsuchiya und Aris (1967): Singular perturbation reduction of

$$\dot{s} = -k_1 e_0 s + (k_1 s + k_{-1}) c,$$

 $\dot{c} = k_1 e_0 s - (k_1 s + k_{-1} + k_2) c.$

Small enzyme concentration; interpretation $e_0 = \varepsilon e_0^*$, $\varepsilon \to 0$. **Scaling**: Set $c^* := c/\varepsilon$; then

$$\dot{s} = \varepsilon(-k_1se_0^* + (k_1s + k_{-1})c^*),$$

 $\dot{c^*} = k_1s - (k_1s + k_{-1} + k_2)c^*$

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ready for application of Tikhonov's theorem. Reduction yields Michaelis-Menten equation.

PART TWO: SINGULAR PERTURBATION REDUCTION FOR CHEMICAL REACTION NETWORKS

Work by and with Alexandra Goeke Lena Nöthen Eva Zerz

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Tikhonov and Fenichel: Basic theorem System with small parameter ε in standard form

$$egin{array}{lll} \dot{x}_1&=f_1(x_1,\,x_2)+arepsilon\,(\dots), &x_1\in D\subseteq \mathbb{R}^r,\ \dot{x}_2&=arepsilon f_2(x_1,\,x_2)+arepsilon^2\,(\dots), &x_2\in G\subseteq \mathbb{R}^s. \end{array}$$

Slow time $\tau = \varepsilon t$: $\varepsilon x'_1 = f_1(x_1, x_2) + \cdots$, $x'_2 = f_2(x_1, x_2) + \cdots$.

Assumptions: (i) Nonempty critical manifold

$$\widetilde{Z} := \left\{ (y_1, y_2)^T \in D \times G; f_1(y_1, y_2) = 0 \right\};$$

(ii) there exists $\nu > 0$ such that every eigenvalue of $D_1 f_1(y_1, y_2)$, $(y_1, y_2) \in \widetilde{Z}$ has real part $\leq -\nu$.

Theorem. There exist T > 0 and a neighborhood of \tilde{Z} in which, as $\varepsilon \to 0$, all solutions converge uniformly to solutions of

$$x_2' = f_2(x_1, x_2), \quad f_1(x_1, x_2) = 0 \quad \text{on } [t_0, T] \quad (t_0 > 0 \text{ arbitrary}).$$

Differential equations for CRN

Typical for chemical reaction networks: Parameter dependent ordinary differential equation

$$\dot{x} = h(x,\pi), \quad x \in \mathbb{R}^n, \quad \pi \in \mathbb{R}^m$$

with polynomial right hand side.

Why? Mass action kinetics, thermodynamical conditions fixed; spatially homogeneous. Parameters: Rate constants, initial concentrations.

Question: How do singular perturbation reductions enter this picture? (A priori: No ε , no slow-fast separation.)

Transfer to standard setting

Parameter dependent system

$$\dot{x} = h(x,\pi)$$

versus

$$\dot{x}_1 = f_1(x_1, x_2) + \varepsilon (\dots), \dot{x}_2 = \varepsilon f_2(x_1, x_2) + \varepsilon^2 (\dots).$$

Preliminary step: For suitable $\hat{\pi}$ (to be determined) consider system

$$\dot{x} = h(x, \hat{\pi} + \varepsilon \rho + \cdots) =: g^{(0)}(x) + \varepsilon g^{(1)}(x) + \varepsilon^2 \cdots$$

Suitability of $\hat{\pi}$ implies: Scenario is *singular*, i.e. the vanishing set of $g^{(0)}$ contains a submanifold Z of dimension s > 0. (*Proof*: Look at standard system when $\varepsilon = 0$.)

Tikhonov-Fenichel: Identification

Proposition. Assume dim Z = s > 0. Then

$$\dot{x} = g^{(0)}(x) + \varepsilon g^{(1)}(x) + \varepsilon^2 \dots$$

admits a coordinate transformation into standard form and subsequent Tikhonov-Fenichel reduction near every point of Z if and only if

(i) rank
$$Dg^{(0)}(x) = r := n - s$$
 for all $x \in Z$;

- (ii) for each $x \in Z$ there exists a direct sum decomposition $\mathbb{R}^n = \operatorname{Ker} Dg^{(0)}(x) \oplus \operatorname{Im} Dg^{(0)}(x);$
- (iii) for each $x \in Z$ the nonzero eigenvalues of $Dg^{(0)}(x)$ have real parts $\leq -\nu < 0$.

Remaining problem: Explicit computation of coordinate transformation is generally impossible.

Tikhonov-Fenichel: Coordinate-free reduction

Singularly perturbed system

$$x' = \varepsilon^{-1}g^{(0)}(x) + g^{(1)}(x) + \dots$$

with $Z \subseteq \mathcal{V}(g^{(0)})$ satisfying conditions (i), (ii) und (iii); $a \in Z$. **Decomposition:** There is a Zariski-open neighborhood U_a of a such that

$$g^{(0)}(x)=P(x)\mu(x),$$

with $\mu(x) \in \mathbb{R}(x)^{r \times 1}$, $P(x) \in \mathbb{R}(x)^{n \times r}$, rank P(a) = r, rank $D\mu(a) = r$, and (w.l.o.g.) $\mathcal{V}(g^{(0)}) \cap U_a = \mathcal{V}(\mu) \cap U_a = Z$. **Reduction:** The system

$$x' = \left[I_n - P(x)A(x)^{-1}D\mu(x)\right]g^{(1)}(x), \text{ with } A(x) := D\mu(x)P(x)$$

is defined on U_a and admits Z as invariant set. The restriction to Z corresponds to the reduction via Tikhonov's theorem as $\varepsilon \to 0$.

Finding suitable parameter values

Definition: We call $\hat{\pi}$ a *Tikhonov-Fenichel parameter value* (*TFPV*) for dimension s ($1 \le s \le n-1$) of $\dot{x} = h(x, \pi)$ if the following hold:

- (i) The vanishing set $\mathcal{V}(h(\cdot, \hat{\pi}))$ of $x \mapsto h(x, \hat{\pi})$ contains a component \widetilde{Y} of dimension s;
- (ii) there is $a \in \widetilde{Y}$ and neighborhood Z of a in \widetilde{Y} such that rank $D_x h(x, \widehat{\pi}) = n s$ and

 $\mathbb{R}^n = \operatorname{Ker} D_x h(x, \widehat{\pi}) \oplus \operatorname{Im} D_x h(x, \widehat{\pi}), \quad \text{for all } x \in Z;$

(iii) the nonzero eigenvalues of $D_x h(a, \hat{\pi})$ have real parts < 0. **Note**: Conditions by copy-and-paste (more or less) from characterization above. Therefore reduction works for small perturbations $\hat{\pi} + \varepsilon \rho + \cdots$.

TFPV: Characterization

Denote the characteristic polynomial of the Jacobian $D_x h(x, \pi)$ by

$$\chi(\tau, x, \pi) = \tau^n + \sigma_{n-1}(x, \pi)\tau^{n-1} + \cdots + \sigma_1(x, \pi)\tau + \sigma_0(x, \pi).$$

Proposition. A parameter value $\hat{\pi}$ is a TFPV with locally exponentially attracting critical manifold $Z = Z_s$ of dimension s > 0, and $x_0 \in Z_s$, if and only if the following hold:

- $\blacktriangleright h(x_0,\widehat{\pi})=0.$
- The characteristic polynomial χ(τ, x, π) satisfies
 (i) σ₀(x₀, π̂) = ··· = σ_{s-1}(x₀, π̂) = 0;
 (ii) all roots of χ(τ, x₀, π̂)/τ^s have negative real parts.
- The system x = h(x, x̂) admits s independent local analytic first integrals at x₀.

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Why the first integrals?

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Proposition. A parameter value $\hat{\pi}$ is a TFPV, and $x_0 \in Z_s$, if and only if the following hold:

► The system ẋ = h(x, π̂) admits s independent local analytic first integrals at x₀.

Underlying reason: Consider Poincaré–Dulac normal form for

$$\dot{y} = By + \cdots, B = \begin{pmatrix} 0 & 0 \\ 0 & B^* \end{pmatrix}, \quad B^* \in \mathbb{R}^{(n-s) \times (n-s)}, \operatorname{Re} \operatorname{Spec} B^* < 0.$$

System admits an *s*-dimensional local manifold of stationary points iff there are *s* independent first integrals. (Convergence? QNF!)

Note. First integrals appear naturally in CRN (stoichiometry).

TFPV: Computation and structure

Properties of TFPV $\hat{\pi}$ for dimension *s*:

- Vanishing set Z of h(·, π̂) has dimension s: "More equations in x than variables"; elimination theory allows a start.
- All nonzero eigenvalues of D_xh(x, π̂), x ∈ Z, have real parts
 < 0: Hurwitz-Routh provides inequalities.
- Further conditions from existence of first integrals.

Theorem. The TFPV for dimension *s* of a polynomial (or rational) system $\dot{x} = h(x, \pi)$ with nonnegative parameters (and *x* in the nonnegative orthant) form a semi-algebraic subset $\Pi_s \subseteq \mathbb{R}^m$.

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TFPV for Michaelis-Menten

System

with Jacobian determinant $d = k_1 k_2 (e_0 - c)$.

Three equations (also d = 0): Eliminate s and c.

Result: A TFPV ($\hat{e}_0, \hat{k}_1, \hat{k}_{-1}, \hat{k}_2$) satisfies

$$\widehat{e}_0 \widehat{k}_2 \widehat{k}_1 = 0.$$

Small perturbations yield all relevant cases:

$$\begin{pmatrix} \varepsilon e_0^* \\ \widehat{k}_1 \\ \widehat{k}_{-1} \\ \widehat{k}_2 \end{pmatrix} \text{ or } \begin{pmatrix} \widehat{e}_0 \\ \varepsilon k_1^* \\ \widehat{k}_{-1} \\ \widehat{k}_2 \end{pmatrix} \text{ or } \begin{pmatrix} \widehat{e}_0 \\ \widehat{k}_1 \\ \widehat{k}_{-1} \\ \varepsilon k_2^* \end{pmatrix} \text{ or } \begin{pmatrix} \widehat{e}_0 \\ \widehat{k}_1 \\ \varepsilon k_{-1} \\ \varepsilon k_2^* \end{pmatrix}$$

Michaelis-Menten: Some reductions

- Small enzyme concentration $e_0 = \varepsilon e_0^*$: Familiar result.
- Slow product formation:

Decomposition $\widehat{g}^{(0)} = P \cdot \mu$ with

$$P = \begin{pmatrix} 1 \\ -1 \end{pmatrix}, \ \mu = k_1 e_0 s - (k_1 s + k_{-1}) c.$$

Reduced equation (on $Z = \mathcal{V}(\mu)$):

$$egin{pmatrix} s' \ c' \end{pmatrix} = rac{1}{k_1(e_0-c)+k_1s+k_{-1}} egin{pmatrix} * & k_1s+k_{-1} \ * & k_1(e_0-c) \end{pmatrix} \cdot egin{pmatrix} 0 \ -k_2^*c \end{pmatrix}.$$

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Further example: Competitive inhibition

Michaelis-Menten network with inhibitor:

$$E + S \stackrel{k_1}{\underset{k_{-1}}{\rightleftharpoons}} C_1 \stackrel{k_2}{\rightharpoonup} E + P, \quad E + I \stackrel{k_3}{\underset{k_{-3}}{\rightleftharpoons}} C_2$$

Mass action kinetics and stoichiometry lead to ODE

$$\dot{s} = k_{-1}c_1 - k_1s(e_0 - c_1 - c_2), \dot{c}_1 = k_1s(e_0 - c_1 - c_2) - (k_{-1} + k_2)c_1, \dot{c}_2 = k_3(e_0 - c_1 - c_2)(i_0 - c_2) - k_{-3}c_2.$$

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Competitive inhibition: TFPV

System

$$\begin{split} \dot{s} &= k_{-1}c_1 - k_1s(e_0 - c_1 - c_2), \\ \dot{c}_1 &= k_1s(e_0 - c_1 - c_2) - (k_{-1} + k_2)c_1, \\ \dot{c}_2 &= k_3(e_0 - c_1 - c_2)(i_0 - c_2) - k_{-3}c_2 \end{split}$$

with Jacobian determinant

$$d(x,\pi) = -k_1k_2(e_0 - c_1 + c_2)(k_{-3} + k_3(i_0 + e_0) - k_3(2c_2 - c_1)).$$

Four equations for three variables: Elimination ideal has radical

$$\mathcal{I} = \langle e_0 k_1 k_2 k_{-3} (k_3^2 (e_0 - i_0)^2 + k_{-3} (k_{-3} + 2k_3 (e_0 + i_0)) \rangle$$

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with single generator. This yields candidates for Π_1 by setting $e_0 = 0$, resp. $k_1 = 0, \ldots$

Competitive inhibition: One of the reductions

System with "small" $e_0 = \varepsilon e_0^*$. Here

$$g^{(0)} = egin{pmatrix} k_1s + k_{-1} & k_1s \ -(k_1s + k_{-1} + k_2) & -k_1s \ -k_3(i_0 - c_2) & -k_3(i_0 - c_2) - k_{-3} \end{pmatrix} \cdot egin{pmatrix} c_1 \ c_2 \end{pmatrix}, \ g^{(1)} = egin{pmatrix} -k_1se_0^* \ k_1se_0^* \ k_3e_0^*(i_0 - c_2) \end{pmatrix}.$$

Critical variety Z defined by $c_1 = c_2 = 0$; reduced system

$$s' = -rac{k_1k_2k_{-3}e_0^*s}{k_1k_{-3}s + (k_{-1}+k_2)(k_3i_0+k_{-3})}, \quad c_1' = c_2' = 0.$$

Note: "Classical" QSS reduction procedure yields the same result.

PART THREE: APPLICATION TO A POPULATION MODEL

Joint work with Niclas Kruff Christian Lax Volkmar Liebscher

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A well-known predator - prey system

Rosenzweig and MacArthur:

$$\dot{B} = \rho B(1-B) - \frac{\alpha \theta}{\theta+B} BR, \dot{R} = -\delta R + \frac{\zeta \alpha \theta}{\theta+B} BR.$$

(B stands for prey, R stands for predator. All parameters positive.)

Questions:

- How to to derive this specific equation from "first principles"?
- Biological interpretation of the parameters?

Approach presented here:

- Start from individual-based (stochastic) model with mass action type interactions ("first principles").
- Pass to ODE ("large volume limit")
- Look at singular perturbation reductions.

Start from individual based model

Three dimensional model with prey *B*, saturated predators *S* and hungry predators *H*; R = H + S.

Differential equation derived from stochastic model:

$$\dot{B} = \rho B(1 - B) - \alpha BH \dot{S} = -\eta S + \gamma BH \dot{H} = \beta S - \delta H + \eta S - \gamma BH$$

Parameters have clear biological interpretation;

e.g. ρ is birth rate of prey, η is rate of transition from saturated to hungry, \ldots

Rosenzweig-MacArthur via reduction

Educated guess: The system

$$\dot{B} = \rho B(1 - B) - \alpha BH \dot{S} = -\eta S + \gamma BH \dot{H} = \beta S - \delta H + \eta S - \gamma BH$$

admits the TFPV

$$\widehat{\pi}:=egin{pmatrix} {f 0}, & \widehat{lpha}, & {f 0}, & \widehat{\gamma}, & {f 0}, & \widehat{\delta} \end{pmatrix}$$
 ;

thus $\rho = \eta = \beta = 0$. Singular perturbation reduction (straightforward) yields Rosenzweig-MacArthur.

Problem (non-mathematical): Biological interpretation of small parameters (slow vs. fast processes).

TFPV and reductions of 3D system

Systematic approach rather than guesswork: Determine all TFPV of

$$\dot{B} = \rho B(1 - B) - \alpha BH \dot{S} = -\eta S + \gamma BH \dot{H} = \beta S - \delta H + \eta S - \gamma BH$$

for dimension s = 2 of the critical manifold.

Necessary conditions (via elimination ideals):

$$\rho\eta\delta = \rho\gamma\delta = \alpha\eta\delta = \rho\gamma\beta = \mathbf{0}.$$

Roughly two dozen cases, not all yielding a TF reduction.

- 15 TF reductions; among these four interesting ones.
- One of these is Rosenzweig-MacArthur (above).
- Another one to be discussed next.

A variant of Rosenzweig-MacArthur

One result of systematic approach: The differential equation

$$\dot{B} = \rho B(1 - B) - \alpha BH \dot{S} = -\eta S + \gamma BH \dot{H} = \beta S - \delta H + \eta S - \gamma BH$$

admits the TFPV

$$\widehat{\pi}:=egin{pmatrix} \mathsf{0}, & \mathsf{0}, & \widehat{\eta}, & \widehat{\gamma}, & \mathsf{0}, & \mathsf{0} \end{pmatrix}$$

with reduced equation (here $\rho = \varepsilon \rho^*$ etc.)

$$\begin{array}{rcl} B' &=& \rho^* B(1-B) - \frac{\alpha^* \theta}{\theta+B} BR \\ R' &=& -\delta^* \frac{\theta}{\theta+B} R + \frac{\beta^*}{\theta+B} BR. \end{array}$$

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More satisfactory from biological (modelling) perspective.

PART FOUR: SOME RECENT RESULTS

Joint work with Elisenda Feliu Niclas Kruff Christian Lax Carsten Wiuf

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"Classical" QSS reduction

"Classical" QSS reduction, following Briggs/Haldane (1925) in more general setting: Consider system

$$\dot{x} = a_0(x) + A_0(x)z + \varepsilon (a_1(x) + A_1(x)z) + \cdots \dot{z} = b_0(x) + B_0(x)z + \varepsilon (b_1(x) + B_1(x)z) + \cdots$$

and assume that $B_0(x)$ is invertible for all x. (Not the most general setting but the most relevant.)

Elimination of z via QSS assumption:

Solve " $\dot{z} = 0$ " and substitute expression for z in first equation.

Observation: Reduction is not necessarily meaningful!

Minimal requirement for consistency:

$$\left(Db_0(x) - DB_0(x)(B_0(x)^{-1}b_0(x))\right)\left(a_0(x) - A_0(x)B_0(x)^{-1}b_0(x)\right) = 0.$$

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"Classical" QSS vs. singular perturbations System

$\dot{x} = a_0(x) + A_0(x)z + \varepsilon (a_1(x) + A_1(x)z) + \cdots$ $\dot{z} = b_0(x) + B_0(x)z + \varepsilon (b_1(x) + B_1(x)z) + \cdots$

with $B_0(x)$ is invertible for all x.

Minimal requirement for consistency of QSS reduction:

$$\left(Db_0 - DB_0(B_0^{-1}b_0)\right)\left(a_0 - A_0B_0^{-1}b_0\right) = 0.$$

(Argument x suppressed.)

Necessary for Tikhonov–Fenichel reduction with critical manifold Y prescribed by b₀(x) + B₀(x)z = 0:

$$a_0(x) - A_0(x)B_0(x)^{-1}b_0(x) = 0$$

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for all x.

Tikhonov-Fenichel reduction

Reduction with prescribed critical manifold Y: With

$$w(x) := B_0(x)^{-1} b_0(x)$$
, thus $z = -w(x)$ on Y

one has

$$\begin{aligned} &b_0(x) + B_0(x)z &= B_0(x) \left(w(x) + z \right), \\ &a_0(x) + A_0(x)z &= A_0(x) \left(w(x) + z \right). \end{aligned}$$

Use reduction theorem for

$$g^{(0)}(x,z) = \begin{pmatrix} a_0(x) + A_0(x)z \\ b_0(x) + B_0(x)z \end{pmatrix}, \quad g^{(1)}(x,z) = \begin{pmatrix} a_1(x) + A_1(x)z \\ b_1(x) + B_1(x)z \end{pmatrix}$$

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Reduced systems

Abbreviation:

$$M := Dw A_0 B_0^{-1} + I_p.$$

Proposition.

(a) The reduced equation by singular perturbation theory, in slow time $\tau = \varepsilon t$, on Y yields the system

$$\begin{array}{rcl} \frac{dx}{d\tau} & = & \left(I_n - A_0 \, B_0^{-1} \, M^{-1} \, Dw \right) \left(a_1 - A_1 w \right) \\ & & - & \left(A_0 \, B_0^{-1} \, M^{-1} \right) \left(b_1 - B_1 w \right). \end{array}$$

(b) The reduction by the classical QSS procedure yields, in slow time, the system

$$\frac{dx}{d\tau} = \left(a_1 - A_1w - A_0B_0^{-1}(b_1 - B_1w)\right) + \varepsilon(\cdots).$$

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Agreement and disagreement

Corollary. The classical QSS reduction agrees with the singular perturbation reduction (up to higher order terms in ε) if and only if

$$A_0B_0^{-1}M^{-1}Dw(A_0B_0^{-1}(B_1w-b_1)-(A_1w-a_1))=0.$$

Given this, Tikhonov's theorem also applies to the QSS reduction.

The condition holds in the following scenarios:

•
$$A_0B_0^{-1}(B_1w - b_1) = A_1w - a_1$$
: Both reductions trivial.

But in general QSS heuristic and singular perturbation reduction yield substantially different results, and reduction by QSS is incorrect.

An incorrect QSS reduction

Popular example: Irreversible Michaelis-Menten equation

$$\dot{s} = -k_1 e_0 s + (k_1 s + k_{-1}) c$$

 $\dot{c} = k_1 e_0 s - (k_1 s + k_{-1}) c - \varepsilon k_2^* c$

with slow product formation; $k_2 = \varepsilon k_2^*$.

Tikhonov-Fenichel reduction on critical manifold *Y* (given by $k_1e_0s - (k_1s + k_{-1})c = 0$):

$$\dot{s} = -rac{k_2 k_1 e_0 s \left(k_1 s + k_{-1}
ight)}{k_{-1} e_0 + (k_1 s + k_{-1})^2}.$$

QSS reduction for complex:

$$\dot{s} = -rac{k_2k_1e_0s}{k_1s+k_{-1}+k_2} = -rac{k_2k_1e_0s}{k_1s+k_{-1}} + \varepsilon(\cdots)$$

These differ significantly (and QSS is wrong)!

Reduction for parameterized critical manifolds

Recall coordinate-free reduction for system

$$x' = \varepsilon^{-1}g^{(0)}(x) + g^{(1)}(x) + \dots$$

on critical manifold Z: Use decomposition $g^{(0)}(x) = P(x)\mu(x)$ to get reduced system

$$x' = Q(x)g^{(1)}(x), \quad Q(x) := \left[I_n - P(x)A(x)^{-1}D\mu(x)\right].$$

Problem: Feasibility for the computation of projection matrix Q. **Alternative approach when parameterization known**: Given open set $W \subseteq \mathbb{R}^s$ and smooth parameterization

$$\Phi \colon W \to Z$$
, rank $D\Phi(v) = s$ for all $v \in W$.

Reduction for parameterized CM

Observation: Every solution x(t) of the reduced system with initial value in $\Phi(W)$ can be written as $x(t) = \Phi(v(t))$. Thus

$$D\Phi(v(t)) v'(t) = x'(t) = Q(\Phi(v(t))) \cdot g^{(1)}(\Phi(v(t))).$$

Theorem.

(a) For every $v \in W$ there exists a unique $R(v) \in \mathbb{R}^{s \times n}$ such that

$$Q(\Phi(v)) = D\Phi(v) \cdot R(v).$$

(b) The reduced system, in parameterized version, is given by

$$v' = R(v) \cdot g^{(1)}(\Phi(v)).$$

(c) For every $x \in Z$ let $L(x) \in \mathbb{R}^{s \times n}$ be of full rank s and such that L(x)P(x) = 0. Then

$$R(v) = (L(\Phi(v)) D\Phi(v))^{-1} L(\Phi(v)).$$

Application to CRN: Fast and slow reactions

Differential equation for network with slow and fast reactions:

$$\dot{x} = N_{\rm f} \cdot (K_{\rm f} \circ x^{Y_{\rm f}}) + \varepsilon N_{\rm s} \cdot (K_{\rm s} \circ x^{Y_{\rm s}})$$

Notation: $N_{\rm f}$ and $N_{\rm s}$ are stoichiometric matrices, and one has rate vectors

$$w_{f}(x) = K_{f} \circ x^{Y_{f}}, \quad w_{s}(x) = K_{s} \circ x^{Y_{s}}$$

with vectors of reaction constants $K_{\rm f}$, $K_{\rm s}$. (Here \circ denotes elementwise product, $x^a = \prod x_i^{a_i}$ for vectors, similarly for matrix exponents.)

Observation: If r denotes the rank of $Dg^{(0)}(x)$, $x \in Z$, then rank $N_{f} \ge r$, but inequality may be strict.

Rank condition. We impose that rank $N_f = \operatorname{rank} Dh^{(0)}(x) = r$, for all $x \in Z$.

Reduction for fast and slow reaction systems

Proposition. Given the system with slow and fast reactions, and a parameterization Φ of the critical manifold, assume the rank condition holds on $\Phi(W)$.

Let $L_f \in \mathbb{R}^{s \times n}$ be a matrix whose rows form a basis of the left-kernel of N_f . Then $R(v) = (L_f D\Phi(v))^{-1} L_f$, and the reduced system is given by

$$v' = (L_{f} D\Phi(v))^{-1} L_{f} N_{s} \cdot (K_{s} \circ \Phi(v)^{Y_{s}}), \qquad v \in W.$$

Remark.

- Parameterization Φ of the stationary points for the fast system is needed. But for many relevant reaction networks such parameterizations are known.
- Closed form reductions like the above are preferrable from an applied perspective.

Thank you for your attention!

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