# REAL PLANAR QUADRATIC SYSTEMS

#### Joan C. Artés

#### Universitat Autònoma de Barcelona

http://www.gsd.uab.cat

Summary of works with J. Llibre (UAB), D. Schlomiuk (Montreal), A. Carlucci/R. Oliveira (Sao Carlos) & N. Vulpe (Moldova)

Joan C. Artés (UAB) REAL PLANAR QUADRATIC SYSTEMS

#### HOW MANY PHASE PORTRAITS OF PLANAR REAL QUADRATIC DIFFERENTIAL SYSTEMS EXISTS?

Joan C. Artés (UAB) REAL PLANAR QUADRATIC SYSTEMS

- A) YES
- SOMEONE DESERVES ABEL PRIZE!!!
- B) NO
- Please, reformulate your question

回 と く ヨ と く ヨ と …

- A) YES
- SOMEONE DESERVES ABEL PRIZE!!!
- B) NO
- Please, reformulate your question

白マ くほ マ イロマー

- A) YES
- SOMEONE DESERVES ABEL PRIZE!!!
- B) NO
- Please, reformulate your question

白マ ヘビマ イロマー

- A) YES
- SOMEONE DESERVES ABEL PRIZE!!!
- B) NO
- Please, reformulate your question

< 注 → < 注 → -

#### HOW MANY PHASE PORTRAITS OF PLANAR REAL QUADRATIC DIFFERENTIAL SYSTEMS EXISTS ...

MODULO LIMIT CYCLES?

・ 回 ト ・ ヨ ト ・ ヨ ト

- HOW MANY PHASE PORTRAITS OF PLANAR REAL QUADRATIC DIFFERENTIAL SYSTEMS EXISTS ...
- MODULO LIMIT CYCLES?

・ 回 ト ・ ヨ ト ・ ヨ ト …

- HOW MANY PHASE PORTRAITS OF PLANAR REAL QUADRATIC DIFFERENTIAL SYSTEMS EXISTS ...
- MODULO LIMIT CYCLES?

・ 回 ト ・ ヨ ト ・ ヨ ト …

 HOW MANY PHASE PORTRAITS OF PLANAR REAL QUADRATIC DIFFERENTIAL SYSTEMS EXISTS ...

MODULO LIMIT CYCLES?

•

回 と く ヨ と く ヨ と …

- HOW MANY PHASE PORTRAITS OF PLANAR REAL QUADRATIC DIFFERENTIAL SYSTEMS EXISTS ...
- ٩
- ٩
- ٩
- MODULO LIMIT CYCLES?

白 と く ヨ と く ヨ と …

- Systems with centers (Vulpe, 1983)
- Systems with a 3rd order weak focus (Artes, Llibre, Schlomiuk, 1984 & 2004)
- 3 Chordal systems (Gasull, Li Ren, Llibre, 1986) (Reyn 1996)
- Systems with two invariant straight lines (Reyn 1987)
- Systems with a single finite singularity (Coll, Gasull, Llibre 1988) (Reyn, 1997)
- Systems with a nilpotent finite singularity (Jager, 1990)
- Ø Systems with finite multiplicity 2 (Reyn, Kooij, 1997)
- Osystems with finite multiplicity 3 (Reyn, Huang, 1997)
- Structurally stable quadratic systems (Artes, Kooij, Llibre, 1998)
- Systems with a 2nd order weak focus (Artes, Llibre, Schlomiuk, 2006)
- Systems with a finite and an infinite saddle-node (Artes, Carlucci, Oliveira, 2015)
- @ Structurally unstable quadratic systems of codimension  $\frac{1}{2}$ ,  $\frac{1}{2}$  or  $\frac{1}{2}$

- Systems with centers (Vulpe, 1983)
- Systems with a 3rd order weak focus (Artes, Llibre, Schlomiuk, 1984 & 2004)
- Ochordal systems (Gasull, Li Ren, Llibre, 1986) (Reyn 1996)
- Systems with two invariant straight lines (Reyn 1987)
- Systems with a single finite singularity (Coll, Gasull, Llibre 1988) (Reyn, 1997)
- Systems with a nilpotent finite singularity (Jager, 1990)
- Ø Systems with finite multiplicity 2 (Reyn, Kooij, 1997)
- Osystems with finite multiplicity 3 (Reyn, Huang, 1997)
- Structurally stable quadratic systems (Artes, Kooij, Llibre, 1998)
- Systems with a 2nd order weak focus (Artes, Llibre, Schlomiuk, 2006)
- Systems with a finite and an infinite saddle-node (Artes, Carlucci, Oliveira, 2015)
- 🕐 Structurally unstable quadratic systems of codimension  $\frac{1}{2}$  ,  $\frac{1}{2}$  so

- Systems with centers (Vulpe, 1983)
- Systems with a 3rd order weak focus (Artes, Llibre, Schlomiuk, 1984 & 2004)
- Schordal systems (Gasull, Li Ren, Llibre, 1986) (Reyn 1996)
- Systems with two invariant straight lines (Reyn 1987)
- Systems with a single finite singularity (Coll, Gasull, Llibre 1988) (Reyn, 1997)
- Systems with a nilpotent finite singularity (Jager, 1990)
- Ø Systems with finite multiplicity 2 (Reyn, Kooij, 1997)
- Osystems with finite multiplicity 3 (Reyn, Huang, 1997)
- Structurally stable quadratic systems (Artes, Kooij, Llibre, 1998)
- Systems with a 2nd order weak focus (Artes, Llibre, Schlomiuk, 2006)
- Systems with a finite and an infinite saddle-node (Artes, Carlucci, Oliveira, 2015)
- @ Structurally unstable quadratic systems of codimension  $\frac{1}{2}$ ,  $\frac{1}{2}$  or  $\frac{1}{2}$

- Systems with centers (Vulpe, 1983)
- Systems with a 3rd order weak focus (Artes, Llibre, Schlomiuk, 1984 & 2004)
- Schordal systems (Gasull, Li Ren, Llibre, 1986) (Reyn 1996)
- Systems with two invariant straight lines (Reyn 1987)
- Systems with a single finite singularity (Coll, Gasull, Llibre 1988) (Reyn, 1997)
- Systems with a nilpotent finite singularity (Jager, 1990)
- Ø Systems with finite multiplicity 2 (Reyn, Kooij, 1997)
- Osystems with finite multiplicity 3 (Reyn, Huang, 1997)
- Structurally stable quadratic systems (Artes, Kooij, Llibre, 1998)
- Systems with a 2nd order weak focus (Artes, Llibre, Schlomiuk, 2006)
- Systems with a finite and an infinite saddle-node (Artes, Carlucci, Oliveira, 2015)
- @ Structurally unstable quadratic systems of codimension  $\frac{1}{2}$ ,  $\frac{1}{2}$  or  $\frac{1}{2}$

- Systems with centers (Vulpe, 1983)
- Systems with a 3rd order weak focus (Artes, Llibre, Schlomiuk, 1984 & 2004)
- Schordal systems (Gasull, Li Ren, Llibre, 1986) (Reyn 1996)
- Systems with two invariant straight lines (Reyn 1987)
- Systems with a single finite singularity (Coll, Gasull, Llibre 1988) (Reyn, 1997)
- Systems with a nilpotent finite singularity (Jager, 1990)
- Ø Systems with finite multiplicity 2 (Reyn, Kooij, 1997)
- Osystems with finite multiplicity 3 (Reyn, Huang, 1997)
- Structurally stable quadratic systems (Artes, Kooij, Llibre, 1998)
- Systems with a 2nd order weak focus (Artes, Llibre, Schlomiuk, 2006)
- Systems with a finite and an infinite saddle-node (Artes, Carlucci, Oliveira, 2015)
- @ Structurally unstable quadratic systems of codimension  $\frac{1}{2}$ ,  $\frac{1}{2}$  or  $\frac{1}{2}$

- Systems with centers (Vulpe, 1983)
- Systems with a 3rd order weak focus (Artes, Llibre, Schlomiuk, 1984 & 2004)
- Schordal systems (Gasull, Li Ren, Llibre, 1986) (Reyn 1996)
- Systems with two invariant straight lines (Reyn 1987)
- Systems with a single finite singularity (Coll, Gasull, Llibre 1988) (Reyn, 1997)
- Systems with a nilpotent finite singularity (Jager, 1990)
- Systems with finite multiplicity 2 (Reyn, Kooij, 1997)
- Osystems with finite multiplicity 3 (Reyn, Huang, 1997)
- Structurally stable quadratic systems (Artes, Kooij, Llibre, 1998)
- Systems with a 2nd order weak focus (Artes, Llibre, Schlomiuk, 2006)
- Systems with a finite and an infinite saddle-node (Artes, Carlucci, Oliveira, 2015)
- @ Structurally unstable quadratic systems of codimension  $\frac{1}{2}$ ,  $\frac{1}{2}$  see

- Systems with centers (Vulpe, 1983)
- Systems with a 3rd order weak focus (Artes, Llibre, Schlomiuk, 1984 & 2004)
- Schordal systems (Gasull, Li Ren, Llibre, 1986) (Reyn 1996)
- Systems with two invariant straight lines (Reyn 1987)
- Systems with a single finite singularity (Coll, Gasull, Llibre 1988) (Reyn, 1997)
- Systems with a nilpotent finite singularity (Jager, 1990)
- Systems with finite multiplicity 2 (Reyn, Kooij, 1997)
- Osystems with finite multiplicity 3 (Reyn, Huang, 1997)
- Structurally stable quadratic systems (Artes, Kooij, Llibre, 1998)
- Systems with a 2nd order weak focus (Artes, Llibre, Schlomiuk, 2006)
- Systems with a finite and an infinite saddle-node (Artes, Carlucci, Oliveira, 2015)
- @ Structurally unstable quadratic systems of codimension  $\frac{1}{2}$ ,  $\frac{1}{2}$  see

- Systems with centers (Vulpe, 1983)
- Systems with a 3rd order weak focus (Artes, Llibre, Schlomiuk, 1984 & 2004)
- Schordal systems (Gasull, Li Ren, Llibre, 1986) (Reyn 1996)
- Systems with two invariant straight lines (Reyn 1987)
- Systems with a single finite singularity (Coll, Gasull, Llibre 1988) (Reyn, 1997)
- Systems with a nilpotent finite singularity (Jager, 1990)
- Systems with finite multiplicity 2 (Reyn, Kooij, 1997)
- Systems with finite multiplicity 3 (Reyn, Huang, 1997)
- Structurally stable quadratic systems (Artes, Kooij, Llibre, 1998)
- Systems with a 2nd order weak focus (Artes, Llibre, Schlomiuk, 2006)
- Systems with a finite and an infinite saddle-node (Artes, Carlucci, Oliveira, 2015)
- @ Structurally unstable quadratic systems of codimension  $\frac{1}{2}$ ,  $\frac{1}{2}$  see

- Systems with centers (Vulpe, 1983)
- Systems with a 3rd order weak focus (Artes, Llibre, Schlomiuk, 1984 & 2004)
- Schordal systems (Gasull, Li Ren, Llibre, 1986) (Reyn 1996)
- Systems with two invariant straight lines (Reyn 1987)
- Systems with a single finite singularity (Coll, Gasull, Llibre 1988) (Reyn, 1997)
- Systems with a nilpotent finite singularity (Jager, 1990)
- Systems with finite multiplicity 2 (Reyn, Kooij, 1997)
- Systems with finite multiplicity 3 (Reyn, Huang, 1997)
- Structurally stable quadratic systems (Artes, Kooij, Llibre, 1998)
- Systems with a 2nd order weak focus (Artes, Llibre, Schlomiuk, 2006)
- Systems with a finite and an infinite saddle-node (Artes, Carlucci, Oliveira, 2015)
- 😰 Structurally unstable quadratic systems of codimension  $\frac{1}{2}$  ,  $\frac{1}{2}$  940

- Systems with centers (Vulpe, 1983)
- Systems with a 3rd order weak focus (Artes, Llibre, Schlomiuk, 1984 & 2004)
- Schordal systems (Gasull, Li Ren, Llibre, 1986) (Reyn 1996)
- Systems with two invariant straight lines (Reyn 1987)
- Systems with a single finite singularity (Coll, Gasull, Llibre 1988) (Reyn, 1997)
- Systems with a nilpotent finite singularity (Jager, 1990)
- Systems with finite multiplicity 2 (Reyn, Kooij, 1997)
- Systems with finite multiplicity 3 (Reyn, Huang, 1997)
- Structurally stable quadratic systems (Artes, Kooij, Llibre, 1998)
- Systems with a 2nd order weak focus (Artes, Llibre, Schlomiuk, 2006)
- Systems with a finite and an infinite saddle-node (Artes, Carlucci, Oliveira, 2015)
- 😰 Structurally unstable quadratic systems of codimension  $\frac{1}{2}$  ,  $\frac{1}{2}$  940

- Systems with centers (Vulpe, 1983)
- Systems with a 3rd order weak focus (Artes, Llibre, Schlomiuk, 1984 & 2004)
- Schordal systems (Gasull, Li Ren, Llibre, 1986) (Reyn 1996)
- Systems with two invariant straight lines (Reyn 1987)
- Systems with a single finite singularity (Coll, Gasull, Llibre 1988) (Reyn, 1997)
- Systems with a nilpotent finite singularity (Jager, 1990)
- Systems with finite multiplicity 2 (Reyn, Kooij, 1997)
- Systems with finite multiplicity 3 (Reyn, Huang, 1997)
- Structurally stable quadratic systems (Artes, Kooij, Llibre, 1998)
- Systems with a 2nd order weak focus (Artes, Llibre, Schlomiuk, 2006)
- Systems with a finite and an infinite saddle-node (Artes, Carlucci, Oliveira, 2015)
- 😰 Structurally unstable quadratic systems of\_codimension 1, 👔 🔊

- Systems with centers (Vulpe, 1983)
- Systems with a 3rd order weak focus (Artes, Llibre, Schlomiuk, 1984 & 2004)
- Schordal systems (Gasull, Li Ren, Llibre, 1986) (Reyn 1996)
- Systems with two invariant straight lines (Reyn 1987)
- Systems with a single finite singularity (Coll, Gasull, Llibre 1988) (Reyn, 1997)
- Systems with a nilpotent finite singularity (Jager, 1990)
- Systems with finite multiplicity 2 (Reyn, Kooij, 1997)
- Systems with finite multiplicity 3 (Reyn, Huang, 1997)
- Structurally stable quadratic systems (Artes, Kooij, Llibre, 1998)
- Systems with a 2nd order weak focus (Artes, Llibre, Schlomiuk, 2006)
- Systems with a finite and an infinite saddle-node (Artes, Carlucci, Oliveira, 2015)
- 2 Structurally unstable quadratic systems of codimension  $1 = -9 \propto 10^{-10}$

To avoid intersections, there are 3 possible ways:

- According number of finite singularities (stopped at  $1 \sim 2$ ).
- According number of finite multiplicity (stopped at 2~3).
- 3 According codimension (currently running at 2).

The study according codimension has been completely done by topological and combinatorial up to now.

白マ イヨマ イヨマ

To avoid intersections, there are 3 possible ways:

- According number of finite singularities (stopped at  $1 \sim 2$ ).
- 2 According number of finite multiplicity (stopped at  $2 \sim 3$ ).
- 3 According codimension (currently running at 2).

The study according codimension has been completely done by topological and combinatorial up to now.

白マ イヨマ イヨマ

To avoid intersections, there are 3 possible ways:

- According number of finite singularities (stopped at  $1 \sim 2$ ).
- **2** According number of finite multiplicity (stopped at  $2 \sim 3$ ).
- According codimension (currently running at 2).

The study according codimension has been completely done by topological and combinatorial up to now.

白マ イヨマ イヨマ

In 2008 J. C. Artés, J. Llibre and N. Vulpe published "Singular points of quadratic systems: A complete classification in the coefficient space  $\mathbb{R}^{12"}$  at International J. of Bifurcation and Chaos. All topological combinations of finite singularities were classified using invariant polynomials. Also focus were distinguished from nodes with those tools.

Assume one can get expressions which capture:

 $I_1 = \delta_1 \delta_2 \delta_3 \delta_4;$ 

If one can obtain these expressions, he will get the discriminants of the polynomial  $x^4 - J_4x^3 + J_3x^2 - J_2x + J_1$ , and their signs will be invariant upon any affine change of coordinates. There is no need of normal forms. They work on the 12-parameter space of coefficients.

Assume one can get expressions which capture:

$$I_1 = \delta_1 \delta_2 \delta_3 \delta_4;$$

If one can obtain these expressions, he will get the discriminants of the polynomial  $x^4 - J_4x^3 + J_3x^2 - J_2x + J_1$ , and their signs will be invariant upon any affine change of coordinates. There is no need of normal forms. They work on the 12-parameter space of coefficients.

Assume one can get expressions which capture:

If one can obtain these expressions, he will get the discriminants of the polynomial  $x^4 - J_4x^3 + J_3x^2 - J_2x + J_1$ , and their signs will be invariant upon any affine change of coordinates. There is no need of normal forms. They work on the 12-parameter space of coefficients.

Assume one can get expressions which capture:

If one can obtain these expressions, he will get the discriminants of the polynomial  $x^4 - J_4x^3 + J_3x^2 - J_2x + J_1$ , and their signs will be invariant upon any affine change of coordinates. There is no need of normal forms. They work on the 12-parameter space of coefficients.

With the use of these invariants, the Sibirschi School in Chisinau (Moldavia) has been able to obtain invariants for every imaginable geometric feature related to quadratic systems.

→ < E > < E >

#### How many finite singularities;

- O How many infinite singularities;
- How many multiple singularities;
- How many weak singularities and their order (foci and/or saddles);
- I How many nilpotent singularities and their type;
- I How is the tangential behavior around every singularity;
- Distinction between different nodes;
- Existence of centers;
- Isochronicity of centers;
- Existence of invariant straight lines;
- Existence of some types of first integrals:

- How many finite singularities;
- How many infinite singularities;
- How many multiple singularities;
- How many weak singularities and their order (foci and/or saddles);
- I How many nilpotent singularities and their type;
- I How is the tangential behavior around every singularity;
- Distinction between different nodes;
- Existence of centers;
- Isochronicity of centers;
- Existence of invariant straight lines;
- Existence of some types of first integrals:

- How many finite singularities;
- How many infinite singularities;
- How many multiple singularities;
- How many weak singularities and their order (foci and/or saddles);
- I How many nilpotent singularities and their type;
- I How is the tangential behavior around every singularity;
- Distinction between different nodes;
- Existence of centers;
- Isochronicity of centers;
- Existence of invariant straight lines;
- Existence of some types of first integrals:

- How many finite singularities;
- How many infinite singularities;
- How many multiple singularities;
- How many weak singularities and their order (foci and/or saddles);
- How many nilpotent singularities and their type;
- I How is the tangential behavior around every singularity;
- Distinction between different nodes;
- Existence of centers;
- Isochronicity of centers;
- Existence of invariant straight lines;
- Existence of some types of first integrals:

- How many finite singularities;
- How many infinite singularities;
- How many multiple singularities;
- How many weak singularities and their order (foci and/or saddles);
- How many nilpotent singularities and their type;
- O How is the tangential behavior around every singularity;
- Distinction between different nodes;
- Existence of centers;
- Isochronicity of centers;
- Existence of invariant straight lines;
- Existence of some types of first integrals:

- How many finite singularities;
- How many infinite singularities;
- How many multiple singularities;
- How many weak singularities and their order (foci and/or saddles);
- How many nilpotent singularities and their type;
- O How is the tangential behavior around every singularity;
- Distinction between different nodes;
- Existence of centers;
- Isochronicity of centers;
- Existence of invariant straight lines;
- Existence of some types of first integrals:

- How many finite singularities;
- How many infinite singularities;
- How many multiple singularities;
- How many weak singularities and their order (foci and/or saddles);
- How many nilpotent singularities and their type;
- O How is the tangential behavior around every singularity;
- Distinction between different nodes;
- Existence of centers;
- Isochronicity of centers;
- Existence of invariant straight lines;
- Existence of some types of first integrals:

A B M A B M

- How many finite singularities;
- How many infinite singularities;
- How many multiple singularities;
- How many weak singularities and their order (foci and/or saddles);
- How many nilpotent singularities and their type;
- O How is the tangential behavior around every singularity;
- Distinction between different nodes;
- Existence of centers;
- Isochronicity of centers;
- Existence of invariant straight lines;
- Existence of some types of first integrals:

A B M A B M

- How many finite singularities;
- How many infinite singularities;
- How many multiple singularities;
- How many weak singularities and their order (foci and/or saddles);
- How many nilpotent singularities and their type;
- O How is the tangential behavior around every singularity;
- Distinction between different nodes;
- Existence of centers;
- Isochronicity of centers;
- Existence of invariant straight lines;
- Existence of some types of first integrals:

(E) (E)

- How many finite singularities;
- How many infinite singularities;
- How many multiple singularities;
- How many weak singularities and their order (foci and/or saddles);
- How many nilpotent singularities and their type;
- O How is the tangential behavior around every singularity;
- Distinction between different nodes;
- Existence of centers;
- Isochronicity of centers;
- Existence of invariant straight lines;
- Existence of some types of first integrals:

물 제 문 제

- How many finite singularities;
- How many infinite singularities;
- How many multiple singularities;
- How many weak singularities and their order (foci and/or saddles);
- How many nilpotent singularities and their type;
- How is the tangential behavior around every singularity;
- Distinction between different nodes;
- Existence of centers;
- Isochronicity of centers;
- Existence of invariant straight lines;
- Existence of some types of first integrals:

We have defined this way of classifying singularities as *Geometrical Classification*. A Geometrical equivalence class has been defined and the singularities (finite and infinite) are classified according to it.

• • = • • = •

• 
$$s, s^{(3)}, n, n^{d}; S, N^{\infty}, N^{\infty}$$
  
•  $f, f^{(3)}, \mathbb{C}, \mathbb{C}; (\frac{0}{2}) SN, S$   
•  $s, n^{d}, f^{(2)}; (\frac{1}{1}) SN, \mathbb{C}, \mathbb{C}$   
•  $c^{\odot}, \mathbb{C}, \mathbb{C}; (\frac{1}{2}) \widehat{P}_{\lambda} E \widehat{P}_{\lambda} - H, S$   
•  $s, s, \widehat{cp}_{(2)}; N^{f}, N^{f}, N^{f}$   
•  $s, s, n^{*} S, N^{\infty}, N^{*}$ 

回とくほとくほと

白 と く ヨ と く ヨ と

S,  $s^{(3)}$ ,  $n, n^d$ ; S,  $N^{\infty}$ ,  $N^{\infty}$ f,  $f^{(3)}$ , ©, ©;  $\binom{0}{2}$ SN, S
s,  $n^d$ ,  $f^{(2)}$ ;  $\binom{1}{1}$ SN, ©, ©
c<sup>0</sup>, ©, ©;  $\binom{1}{2}$ P<sub>0</sub> E P<sub>0</sub> - H, S
s, s,  $cp_{(2)}$ ;  $N^f$ ,  $N^f$ ,  $N^f$ 

S, 
$$s^{(3)}$$
, n,  $n^d$ ; S,  $N^{\infty}$ ,  $N^{\infty}$ 
f,  $f^{(3)}$ , ©, ©;  $(\overline{{0} \atop {2}})$  SN, S
s,  $n^d$ ,  $f^{(2)}$ ;  $(\overline{{1} \atop {1}})$  SN, ©, ©
s,  $c^{\odot}$ , ©, ©;  $(\widehat{{1} \atop {2}})$   $\widehat{P}_{\lambda} E \widehat{P}_{\lambda} - H$ , S
s, s,  $\widehat{cp}_{(2)}$ ;  $N^f$ ,  $N^f$ 
s, s, n, n\*; S,  $N^{\infty}$ ,  $N^*$ 

マット くぼう くほう

S, 
$$s^{(3)}$$
,  $n, n^d$ ; S,  $N^{\infty}$ ,  $N^{\infty}$ 
f,  $f^{(3)}$ , ©, ©;  $(\overline{\stackrel{0}{2}})$  SN, S
s,  $n^d$ ,  $f^{(2)}$ ;  $(\overline{\stackrel{1}{1}})$  SN, ©, ©
c<sup>o</sup>, ©, ©;  $(\widehat{\stackrel{1}{2}})$   $\widehat{P}_{\lambda} E \widehat{P}_{\lambda} - H$ , S
s, s,  $\widehat{cp}_{(2)}$ ;  $N^f$ ,  $N^f$ ,  $N^f$ 
s, s,  $n, n^*$ ; S,  $N^{\infty}$ ,  $N^*$ 

白 と く ヨ と く ヨ と

S, 
$$s^{(3)}$$
,  $n, n^d$ ;  $S, N^{\infty}, N^{\infty}$ 
 General form:
  $f, f^{(3)}, \mathbb{C}, \mathbb{C}; [\frac{0}{2}]SN, S$ 
 S,  $n^d, f^{(2)}; [\frac{1}{1}]SN, \mathbb{C}, \mathbb{C}$ 
 S,  $n^c, \mathbb{C}, \mathbb{C}; [\frac{1}{2}] \widehat{P}_{\lambda} E \widehat{P}_{\lambda} - H, S$ 
 S,  $s, \widehat{cp}_{(2)}; N^f, N^f, N^f$ 
 S,  $s, n, n^*; S, N^{\infty}, N^*$ 

マット くぼう くほう

#### **BIFURCATION DIAGRAM** (1765 configurations)

$$\begin{array}{c} \underbrace{\mu_{0}=\mu_{1}=0,}_{\substack{\mu_{2}\neq0=\kappa\\ \underline{\mu_{2}\neq0=\kappa\\ W_{7}=0}}} \underbrace{\widetilde{M}\neq0}_{\widetilde{W}=0} \xrightarrow{\widetilde{B}_{1}\neq0} s, n^{d}; \left(\frac{1}{2}\right) \widehat{P}_{\lambda}E\widehat{P}_{\lambda}-H, \left(\frac{1}{1}\right)SN}_{\substack{\mu_{2}\neq0=\kappa\\ \underline{\mu_{2}\neq0=\kappa\\ W_{7}=0}}} \underbrace{\widetilde{M}=0}_{\widetilde{W}=0} \xrightarrow{\widetilde{\sigma}\neq0} s, f; \left(\frac{2}{3}\right) \widehat{P}_{\lambda}\widehat{P}-\widehat{P}_{\lambda}\widehat{P}}_{\underset{\widetilde{W}=0}{\widetilde{\sigma}\neq0}}_{\substack{W_{9}>0\\ \overline{\sigma}=0\\ W_{9}>0}} s, n; \left(\frac{2}{3}\right) \widehat{P}_{\lambda}\widehat{P}-\widehat{P}_{\lambda}\widehat{P}}_{\underset{\widetilde{W}=0}{\widetilde{\mu}\neq0}}_{\underset{W_{9}=0}{\widetilde{\sigma}\neq0}} s, n^{d}; \left(\frac{2}{3}\right) \widehat{P}_{\lambda}\widehat{P}-\widehat{P}_{\lambda}\widehat{P}}_{\underset{W_{9}=0}{\widetilde{\mu}\neq0}}_{\underset{W_{9}=0}{\widetilde{\sigma}\neq0}} s, n^{d}; \left(\frac{2}{3}\right) \widehat{P}_{\lambda}\widehat{P}-\widehat{P}_{\lambda}\widehat{P}}_{\underset{W_{9}=0}{\widetilde{\mu}\neq0}}_{\underset{W_{9}=0}{\widetilde{\sigma}\neq0}} s, n^{d}; \left(\frac{2}{3}\right) \widehat{P}_{\lambda}\widehat{P}-\widehat{P}_{\lambda}\widehat{P}}_{\underset{W_{9}=0}{\widetilde{\mu}\neq0}}_{\underset{W_{9}=0}{\widetilde{\sigma}\neq0}} s, n^{d}; \left(\frac{2}{3}\right) \widehat{P}_{\lambda}\widehat{P}-\widehat{P}_{\lambda}\widehat{P}}_{\underset{W_{9}=0}{\widetilde{\mu}\neq0}}_{\underset{W_{9}=0}{\widetilde{\mu}\neq0}} s, n^{d}; \left(\frac{2}{3}\right) \widehat{P}_{\lambda}\widehat{P}-\widehat{P}_{\lambda}\widehat{P}}_{\underset{W_{9}=0}{\widetilde{\mu}\neq0}}_{\underset{W_{9}=0}{\widetilde{\mu}\neq0}} s, n^{d}; \left(\frac{2}{3}\right) \widehat{P}_{\lambda}\widehat{P}-\widehat{P}_{\lambda}\widehat{P}}_{\underset{W_{9}=0}{\widetilde{\mu}\neq0}}_{\underset{W_$$

The full diagram takes 70 pages to be written.

コマ ヘビマ ヘロマー

# **REDUCTION TO TOPOLOGICAL (208 configurations)**

$$\begin{array}{c} \mu_{0}=0, \\ \mu_{1}=0, \\ \mu_{2}\neq 0\\ \widetilde{K}=0 \\ \widetilde{K}=0 \\ \widetilde{L}=0 \\ \widetilde{L}=0 \\ \widetilde{L}=0 \\ \widetilde{L}=0 \\ \widetilde{L}=0 \\ \widetilde{K}=0 \\ \end{array} \begin{array}{c} \eta < 0 \\ \mu_{2}\widetilde{L} < 0 \\$$

This "only" needs 13 pages.

白 マイ キャー・

#### 157 configurations completed;

- 2 Many configurations have a single possible phase portrait;
- Only some few configurations have more than 10 phase portraits;
- 22 easy to complete;
- 3 29 on work;
- 814 phase portraits up to now, 231 of them from those uncomplete 29 families;
- maximum of phase portraits in one completed configuration (up to now): 97;

高 ト イ ヨ ト イ ヨ ト

## CURRENT STATE OF RESEARCH

#### 157 configurations completed;

- Many configurations have a single possible phase portrait;
- Only some few configurations have more than 10 phase portraits;
- 22 easy to complete;
- 3 29 on work;
- 814 phase portraits up to now, 231 of them from those uncomplete 29 families;
- maximum of phase portraits in one completed configuration (up to now): 97;

高 ト イ ヨ ト イ ヨ ト

- 157 configurations completed;
- Many configurations have a single possible phase portrait;
- Only some few configurations have more than 10 phase portraits;
- 22 easy to complete;
- 3 29 on work;
- 814 phase portraits up to now, 231 of them from those uncomplete 29 families;
- maximum of phase portraits in one completed configuration (up to now): 97;

伺 と く き と く き と

- 157 configurations completed;
- Many configurations have a single possible phase portrait;
- Only some few configurations have more than 10 phase portraits;
- 22 easy to complete;
- 3 29 on work;
- 814 phase portraits up to now, 231 of them from those uncomplete 29 families;
- maximum of phase portraits in one completed configuration (up to now): 97;

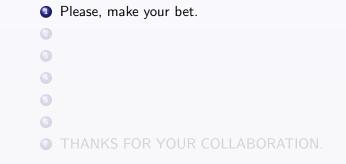
白マ イヨマ イヨマ

- 157 configurations completed;
- Many configurations have a single possible phase portrait;
- Only some few configurations have more than 10 phase portraits;
- 22 easy to complete;
- 3 29 on work;
- 814 phase portraits up to now, 231 of them from those uncomplete 29 families;
- maximum of phase portraits in one completed configuration (up to now): 97;

白 と く ヨ と く ヨ と

- 157 configurations completed;
- Many configurations have a single possible phase portrait;
- Only some few configurations have more than 10 phase portraits;
- 22 easy to complete;
- 3 29 on work;
- 814 phase portraits up to now, 231 of them from those uncomplete 29 families;
- maximum of phase portraits in one completed configuration (up to now): 97;

- 157 configurations completed;
- Many configurations have a single possible phase portrait;
- Only some few configurations have more than 10 phase portraits;
- 22 easy to complete;
- 3 29 on work;
- 814 phase portraits up to now, 231 of them from those uncomplete 29 families;
- maximum of phase portraits in one completed configuration (up to now): 97;



Joan C. Artés (UAB) REAL PLANAR QUADRATIC SYSTEMS

<ロ> <四> <四> <四> <三< => < 三> <三< => = 三

2

Please, make your bet.

567 THANKS FOR YOUR COLLABORATION

<ロ> <四> <四> <四> <三< => < 三> <三< => = 三

- Please, make your bet.
- 2
- 3
- 6
- THANKS FOR YOUR COLLABORATION.

<ロ> <四> <四> <四> <三< => < 三> <三< => = 三



Please, make your bet.

2

3

3

5

THANKS FOR YOUR COLLABORATION

Joan C. Artés (UAB) REAL PLANAR QUADRATIC SYSTEMS

(ロ) (四) (ヨ) (ヨ) (ヨ)

Please, make your bet.

2

3

4

5

THANKS FOR YOUR COLLABORATION.

Joan C. Artés (UAB) REAL PLANAR QUADRATIC SYSTEMS

(ロ) (四) (ヨ) (ヨ) (ヨ)

- Please, make your bet.
- 2
- 3
- 3
- 5
- THANKS FOR YOUR COLLABORATION

<ロ> (四) (四) (三) (三) (三) (三)

Please, make your bet.

2

3

4

5

0

THANKS FOR YOUR COLLABORATION.

・ロト ・回ト ・ヨト ・ヨト

æ